## Multiplicative Updates & the Winnow Algorithm

Machine Learning



## Where are we?

- Still looking at linear classifiers
- Still looking at mistake-bound learning
- We have seen the Perceptron update rule

• Receive an input ( $\boldsymbol{x}_i, y_i$ )

• if sgn( $\mathbf{w}_t^T \mathbf{x}_i$ )  $\neq y_i$ : Update  $\mathbf{w}_{t+1} \leftarrow \mathbf{w}_t + y_i \mathbf{x}_i$ 

 The Perceptron update is an example of an *additive* weight update

# This lecture

- The Winnow Algorithm
- Winnow mistake bound
- Generalizations

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# The setting

- Recall linear threshold units
  - Prediction = +1 if  $w^T x \ge \theta$
  - Prediction = -1 if  $w^T x < \theta$
- The Perceptron mistake bound is  $(R/\gamma)^2$ 
  - For Boolean functions with n attributes,  $R^2 = n$ , so basically O(n)

#### • *Motivating question*:

Suppose we know that even though the number of attributes is n, the number of relevant attributes is k, which is much less than n Can we improve the mistake bound?

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- The elimination algorithm will work:
  - Start with h(x) =  $x_1 \lor x_2 \lor \cdots \lor x_{1024}$
  - Mistake on a negative example: Eliminate all attributes in the example from your hypothesis function h
    - Suppose we have an example  $x_{100} = 1$ ,  $x_{301} = 1$ , label = -1
    - Simple update: just eliminate these two variables from the function
  - Will never make mistakes on a positive example. Why?

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- But we know that our function is a k-disjunction (here k = 2)
  - And there are only  $C(n, k) \cdot 2^k \approx n^k 2^k$  such functions
  - The Halving algorithm will make k log(n) mistakes
  - Can we realize this bound with an efficient algorithm?

## Multiplicative updates

- Let's use linear classifiers with a different update rule
  - Remember: Perceptron will make O(n) mistakes on Boolean functions
- The idea: Weights should be promoted and demoted via multiplicative, rather than additive, updates

Littlestone 1988

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Given a training set D = {(x, y)},  $x \in \{0,1\}^n$ ,  $y \in \{-1,1\}$ 

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- 2. For each training example (x, y):
  - Predict  $y' = \operatorname{sgn}(\mathbf{w}^{\mathsf{T}}\mathbf{x} \theta)$

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  - If y = +1 and y' = -1 then:
- Promotion Update each weight  $w_i \leftarrow 2w_i$  only for those features  $x_i$  that are 1 Else if y = -1 and y' = +1 then:

**Demotion** • Update each weight  $w_i \leftarrow w_i/2$  only for those features  $x_i$  that are 1

 $f = x_1 \vee x_2 \vee x_{1023} \vee x_{1024}$  Initialize  $\theta = 1024$ , w = (1,1,1,1,...,1)

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Example	Prediction	Error?	Weights
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No changes until there are mistakes

 $f = x_1 \vee x_2 \vee x_{1023} \vee x_{1024}$  Initialize  $\theta = 1024$ , w = (1,1,1,1,...,1)

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Promote x<sub>1</sub>

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Promote x<sub>2</sub>

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<i>x</i> =(1,1,1,,0), <i>y</i> =+1	$\mathbf{w}^{T} x < \theta$	Yes	<b>w</b> = ( <b>4</b> , <b>4</b> , <b>2</b> ,1,1)

Promote x<sub>1</sub>, x<sub>2</sub> and x<sub>3</sub>

...

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...

Suppose after many steps, **w** = (512,256,512,512...,512)

...

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			w = ( <b>512,256</b> ,512,512, <b>512</b> )
<i>x</i> =(0,0,1,1,,0), <i>y</i> =-1	$\mathbf{w}^{ extsf{T}} oldsymbol{x} \geq  heta$	Yes	<b>w</b> = (512,256, <b>256</b> , <b>256</b> ,512)

Demote  $x_3$  and  $x_4$ 

 $f = x_1 \vee x_2 \vee x_{1023} \vee x_{1024}$  Initialize  $\theta = 1024$ , w = (1,1,1,1...,1)

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			w = ( <b>512,256</b> ,512,512, <b>512</b> )
<i>x</i> =(0,0,1,1,,0), <i>y</i> =-1	$\mathbf{w}^{ extsf{T}} oldsymbol{x} \geq  heta$	Yes	<b>w</b> = (512,256, <b>256</b> , <b>256</b> ,512)
<i>x</i> =(0,0,0,,1), <i>y</i> =+1	$\mathbf{w}^{T} x < \theta$	Yes	<b>w</b> = (512,256,256,256, <b>1024</b> )

Eventually, the algorithm will converge to something like w = (1024,1024,16,2..., 1024,1024)

## The multiplicative update

Widely used (and re-re-discovered) in various fields

- Winnow (and the Majority Weighted algorithm)
- We will see the AdaBoost algorithm
- Shows up in economics and game theory (from the 1950s)
- Computational Geometry
- Operations research
- Many more...

See: Sanjeev Arora, Elad Hazan and Satyen Kale, *The Multiplicative Weights Update Method: a Meta Algorithm and Applications,* for a survey

# This lecture

- The Winnow Algorithm
- Winnow mistake bound
- Generalizations

Given a training set D = {( $\boldsymbol{x}, y$ )},  $\boldsymbol{x} \in \Re^n$ ,  $y \in$  {-1,1}

- 1. Initialize: **w** = (1,1,1,1...,1)  $\in \Re^{n, \theta} = n$
- 2. For each training example (x, y):
  - Predict  $y' = \operatorname{sgn}(\mathbf{w}^{\mathsf{T}} \mathbf{x} \theta)$
  - If y = +1 and y' = -1 then:
    - Update each weight  $\mathbf{w}_i \leftarrow 2\mathbf{w}_i$  only for those features  $x_i$  that are 1 Else if y = -1 and y' = +1 then:
      - Update each weight  $\mathbf{w}_{\mathsf{i}} \leftarrow \mathbf{w}_{\mathsf{i}}/2$  only for those features  $x_i$  that are 1

## Winnow mistake bound

We will analyze the simple case of *k*-*disjunctions* 

#### Theorem

The Winnow algorithm learns the class of k-disjunctions with n Boolean variables in the Mistake bound model, making O(k log n) mistakes.

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#### Theorem

The Winnow algorithm learns the class of k-disjunctions with n Boolean variables in the Mistake bound model, making O(k log n) mistakes.

Implications:

- 1. Recall: The Perceptron mistake bound is O(n), "throwing lots of features at the problem" can hurt learning
- Winnow is *attribute efficient* because it only has a log dependency on n.
  Only a small penalty for trying out lots of features

## Proof

Theorem: Winnow will make at most O(k log n) mistakes with k-disjunctions

Our target functions are k-disjunctions

#### Strategy

#### Total mistakes = mistakes on positive examples

+

mistakes on negative examples

#### Get mistake bound by upper bounding each separately

Theorem: Winnow will make at most O(k log n) mistakes with k-disjunctions

Our target functions are k-disjunctions

#### Strategy Total mistakes = mistakes on positive examples $m^+$ + mistakes on negative examples $m^-$

Proof

#### Get mistake bound by upper bounding each separately

# 1. Mistakes on positives

(The true label is positive, the prediction is negative)

Theorem: Winnow will make at most O(k log n) mistakes with k-disjunctions

Our target functions are k-disjunctions

- A mistake on a positive example will double the weights for *at least* one of the relevant attributes. Why?
   Because a positive example will have at least one relevant attribute
- We initialized our weight vector with 1's and the threshold  $\theta$  is always fixed to n
- How many times can a relevant attribute get promoted (i.e. doubled) before it hits n?
  - 1 + log(n) times. After that, it will cross  $\theta$

Number of mistakes on positive examples  $m^+ \leq k \left(1 + \log(n)\right)$ 

# 2. Mistakes on negatives

(The true label is negative, the prediction is positive)

Theorem: Winnow will make at most O(k log n) mistakes with k-disjunctions

Our target functions are k-disjunctions

There is *no relevant feature* in the example, yet the dot product of weights and features was more than n

Halve all the weights of the features in this example. *No relevant feature* will ever get demoted.

But will irrelevant features ever get promoted (i.e their weights doubled)?

Yes. If an irrelevant feature shows up in a positive example, it may get promoted

Contrast: Relevant features will only get promoted and never demoted We need a different way to count mistakes on negatives

## 2. Mistakes on negatives

Let's use a different strategy

Theorem: Winnow will make at most O(k log n) mistakes with k-disjunctions

Our target functions are k-disjunctions

Track the sum of all weights over time:  $TW_t = \sum_{i=1}^{n} w_i^t$ 

- 1. The weights are never negative, neither is their sum  $TW_t > 0$
- 2. The initial value of the sum is n (because all weights are initialized to 1)

 $TW_0 = n$ 

Let's use a different strategy

Theorem: Winnow will make at most O(k log n) mistakes with k-disjunctions

Our target functions are k-disjunctions

Track the sum of all weights over time:  $TW_t = \sum_{i=1}^{t} w_i^t$ 

3. What happens to  $TW_t$  when there is a mistake on a positive example?  $TW_{t+1} < TW_t + n$  Why?

Total increase because of positive examples  $< nm^+$ 

Let's use a different strategy

Theorem: Winnow will make at most O(k log n) mistakes with kdisjunctions

Our target functions are k-disjunctions

Track the sum of all weights over time:  $TW_t = \sum_{i=1}^{t} w_i^t$ 

4. What happens to  $TW_t$  when there is a mistake on a negative example?

$$TW_{t+1} < TW_t - \frac{\pi}{2}$$
 Why?

Total *decrease* because of negative examples  $< \frac{n}{2}m^{-1}$ 

## 2. Mistakes on negatives

Let's use a different strategy

Theorem: Winnow will make at most O(k log n) mistakes with k-disjunctions

Our target functions are k-disjunctions

What we know:

 $TW_t > 0 \qquad TW_0 = n$ 

Total increase because of positive examples  $< nm^+$ 

Total decrease because of negative examples  $< \frac{n}{2}m^{-}$ 

Putting these together:  $0 < TW_t < n + nm^+ - \frac{n}{2}m^-$ 

Number of mistakes on negative examples  $m^- < 2(1 + m^+)$ 

## 3. Mistake bound

Theorem: Winnow will make at most O(k log n) mistakes with k-disjunctions

Our target functions are k-disjunctions

Mistakes on positive examples:  $m^+ \le k (1 + \log(n))$ Mistakes on negative examples:  $m^- < 2(1 + m^+)$ 

Total number of mistakes = 
$$m^+ + m^- < m^+ + 2(1 + m^+)$$
  
 $< 2 + 3k (1 + \log(n))$ 

Number of mistakes Winnow will make on k-disjunctions =  $O(k \log(n))$ 

# This lecture

- The Winnow Algorithm
- Winnow mistake bound
- Generalizations

## What can Winnow represent?

The version we saw can only learn monotone functions

- Why?





## **Balanced Winnow**

- Duplicate the variables
  - If  $x_i^+$  represents a Boolean variable, then, introduce a new variable  $x_i^-$  to denote its negation
  - That is, learn a monotone function over the 2n variables ( $w^{\rm +}_{i}$  for each  $x^{\rm +}_{i}$  and  $w^{\rm -}_{i}$  for each  $x^{\rm -}_{i}$ )
  - Effective weight vector is the difference of the two. That is, prediction is performed as:
    - Prediction = +1 if  $(\mathbf{w}^+ \mathbf{w}^-)^T \mathbf{x} \ge \theta$ , else prediction = -1
  - Modify the update rule so that whenever  $w_i$  is promoted,  $w^{\text{-}}_i$  should be demoted and vice versa.
- Can learn any linear threshold unit

## **Balanced Winnow**

Given a training set D = {( $m{x}, y$ )},  $m{x} \in \Re^n$ ,  $y \in$  {-1,1}

- 1. Initialize:  $w^+ = (1, 1, 1, 1, ..., 1), w^- = (1, 1, 1, 1, ..., 1) \in \Re^{n, \theta} = n$
- 2. For each training example (x, y):
  - Predict  $y' = \operatorname{sgn}((\mathbf{w}^+ \mathbf{w}^-)^T x \theta)$
  - If y = +1 and y' = -1 then:
    - Update weight  $\mathbf{w}_{i}^{+} \leftarrow 2\mathbf{w}_{i}^{+}$  only for those features  $x_{i}$  that are 1
    - Update weight  $\mathbf{w}_i \leftarrow \mathbf{w}_i/2$  only for those features  $x_i$  that are 1 Else if y = -1 and y' = +1 then:
      - Update weight  $\mathbf{w}_{i}^{+} \leftarrow \mathbf{w}_{i}^{+}/2$  only for those features  $x_{i}$  that are 1
      - Update weight  $\mathbf{w}_i \leftarrow 2\mathbf{w}_i$  only for those features  $x_i$  that are 1

Downsides of this approach?

## Perceptron and Winnow

- Both are:
  - Mistake bound algorithms
  - Learn linear threshold units
  - Are generally robust
- Which algorithm should you use??
  - Multiplicative algorithms: If you believe that the hidden target function is sparse
  - Additive algorithms: If you believe that your target function could be a dense vector
    - What if the target function is a dense vector but each example is sparse? (If time permits, we will see additive algorithms that are designed for this regime)

# Summary: What Winnow so far?

- A multiplicative update algorithm
  - Learns a linear classifier when very few attributes are relevant
  - Mistake bound only weakly (logarithmically) depends on the number of attributes
- Robust to both classification and attribute noise
  - In general, instead of multiplying and dividing by 2, we could do so by  $(1 + \epsilon)$  for some small  $\epsilon$