

Discriminative Learning over Constrained Latent Representations

Ming-Wei Chang, Dan Goldwasser, Dan Roth and Vivek Srikumar

Computer Science Department, University of Illinois at Urbana-Champaign

An one minute version of the talk

What we did

- Provide a *general recipe* for many important NLP problems
- Our algorithm: **L**earning over **C**onstrained **L**atent **R**epresentations

An one minute version of the talk

What we did

- Provide a *general recipe* for many important NLP problems
- Our algorithm: **L**earning over **C**onstrained **L**atent **R**epresentations

Example NLP problems

- Transliteration (Klementiev and Roth 2008),
- Textual entailment (RTE) (Dagan, Glickman, and Magnini 2006)
- Paraphrase identification (Dolan, Quirk, and Brockett 2004)
- Question Answering, and many more!

An one minute version of the talk

What we did

- Provide a *general recipe* for many important NLP problems
- Our algorithm: **L**earning over **C**onstrained **L**atent **R**epresentations

Example NLP problems

- Transliteration (Klementiev and Roth 2008),
- Textual entailment (RTE) (Dagan, Glickman, and Magnini 2006)
- Paraphrase identification (Dolan, Quirk, and Brockett 2004)
- Question Answering, and many more!

Problems of Interests

Binary classification tasks that require an intermediate representation

Example task: Paraphrase Identification

Yes/NO

Alan
will
face
murder
charges
,
Bob
said

Bob
said
Alan
will
be
charged
with
murder

- Q: Are sentence 1 and sentence 2 paraphrases of each other?

Example task: Paraphrase Identification

Yes/NO

Alan
will
face
murder
charges
,
Bob
said

Bob
said
Alan
will
be
charged
with
murder

- Q: Are sentence 1 and sentence 2 paraphrases of each other?
 - Yes, but why?

Example task: Paraphrase Identification

Yes/NO

Alan
will
face
murder
charges
,
Bob
said

Bob
said
Alan
will
be
charged
with
murder

- Q: Are sentence 1 and sentence 2 paraphrases of each other?
 - Yes, but why?
 - They carry the same information!

Example task: Paraphrase Identification

Yes/NO

Alan
will
face
murder
charges
,
Bob
said

Bob
said
Alan
will
be
charged
with
murder

- Q: Are sentence 1 and sentence 2 paraphrases of each other?
 - Yes, but why?
 - They carry the same information!
- Justifying the decision requires **an intermediate representation**

Example task: Paraphrase Identification

Yes/NO

Alan will face murder charges , Bob said

Bob said Alan will be charged with murder

- Q: Are sentence 1 and sentence 2 paraphrases of each other?
 - Yes, but why?
 - They carry the same information!
- Justifying the decision requires **an intermediate representation**

Example task: Paraphrase Identification

Yes/NO

Alan will face murder charges , Bob said

Bob said Alan will be charged with murder

- Q: Are sentence 1 and sentence 2 paraphrases of each other?
 - Yes, but why?
 - They carry the same information!
- Justifying the decision requires **an intermediate representation**
- Just an example; the real intermediate representation is more complicated

Example task: Paraphrase Identification

Yes/NO

Alan will face murder charges , Bob said

Bob said Alan will be charged with murder

- Q: Are sentence 1 and sentence 2 paraphrases of each other?
 - Yes, but why?
 - They carry the same information!
- Justifying the decision requires **an intermediate representation**
- Just an example; the real intermediate representation is more complicated

Problem of interests

- Binary output problem: $y \in \{-1, 1\}$
- Intermediate representation: h
 - Some structure that justifies the positive label**
 - The intermediate representation is **latent** (not present in the data)

Limitations of existing approaches: two-stage approach

Most systems: a two-stage approach

Stage 1: Generate the intermediate representation

Obtain intermediate representation \rightarrow Fix it (ignore the second stage) !

$$X \rightarrow H$$

Limitations of existing approaches: two-stage approach

Most systems: a two-stage approach

Stage 1: Generate the intermediate representation

Obtain intermediate representation \rightarrow Fix it (ignore the second stage) !

$$X \rightarrow H$$

Stage 2: Classification based on the intermediate representation

Extract features using the fixed representation and learn:

$$\Phi(X, H) \rightarrow Y$$

Limitations of existing approaches: two-stage approach

Most systems: a two-stage approach

Stage 1: Generate the intermediate representation

Obtain intermediate representation \rightarrow Fix it (ignore the second stage) !

$$X \rightarrow H$$

Stage 2: Classification based on the intermediate representation

Extract features using the fixed representation and learn:

$$\Phi(X, H) \rightarrow Y$$

Problem: the intermediate representation **ignores** the binary task

Limitations of existing approaches: two-stage approach

Most systems: a two-stage approach

Stage 1: Generate the intermediate representation

Obtain intermediate representation \rightarrow Fix it (ignore the second stage) !

$$X \rightarrow H$$

Stage 2: Classification based on the intermediate representation

Extract features using the fixed representation and learn:


$$\Phi(X, H) \rightarrow Y$$

Problem: the intermediate representation **ignores** the binary task

Limitations of existing approaches: inference

- Observation: decisions on intermediate representation are interdependent

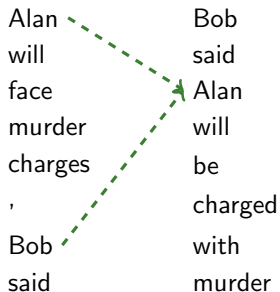
| | |
|---------|---------|
| Alan | Bob |
| will | said |
| face | Alan |
| murder | will |
| charges | be |
| , | charged |
| Bob | with |
| said | murder |



Limitations of existing approaches: inference

- Observation: decisions on intermediate representation are interdependent


| | |
|---------|---------|
| Alan | Bob |
| will | said |
| face | Alan |
| murder | will |
| charges | be |
| , | charged |
| Bob | with |
| said | murder |



Limitations of existing approaches: inference

- Observation: decisions on intermediate representation are interdependent

| | |
|---------|---------|
| Alan | Bob |
| will | said |
| face | Alan |
| murder | will |
| charges | be |
| , | charged |
| Bob | with |
| said | murder |



Limitations of existing approaches: inference

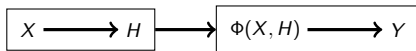
- Observation: decisions on intermediate representation are interdependent

| | |
|---------|---------|
| Alan | Bob |
| will | said |
| face | Alan |
| murder | will |
| charges | be |
| , | charged |
| Bob | with |
| said | murder |

- Many frameworks use custom designed inference procedures
- Difficult to add linguistic intuition/constraints on the intermediate representation
- Difficult to generalize to other tasks

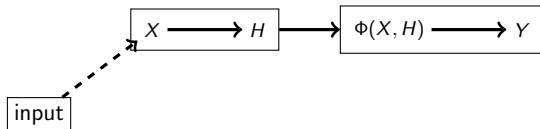
Learning Constrained Latent Representation (LCLR)

- **Property 1:** Jointly learn intermediate representations and labels



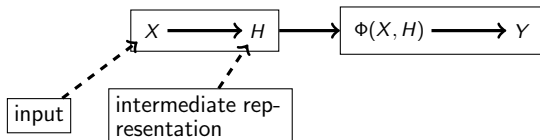
Learning Constrained Latent Representation (LCLR)

- **Property 1:** Jointly learn intermediate representations and labels



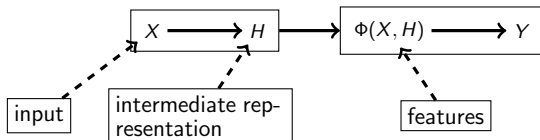
Learning Constrained Latent Representation (LCLR)

- **Property 1:** Jointly learn intermediate representations and labels



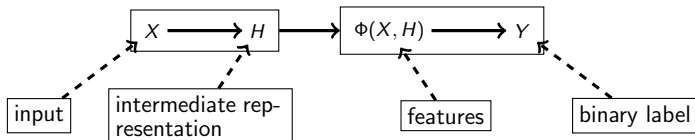
Learning Constrained Latent Representation (LCLR)

- **Property 1:** Jointly learn intermediate representations and labels



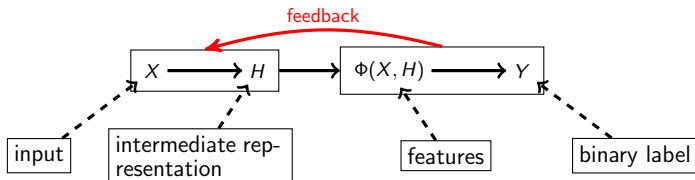
Learning Constrained Latent Representation (LCLR)

- **Property 1:** Jointly learn intermediate representations and labels



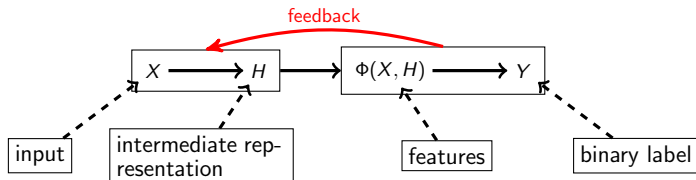
Learning Constrained Latent Representation (LCLR)

- **Property 1:** Jointly learn intermediate representations and labels



Learning Constrained Latent Representation (LCLR)

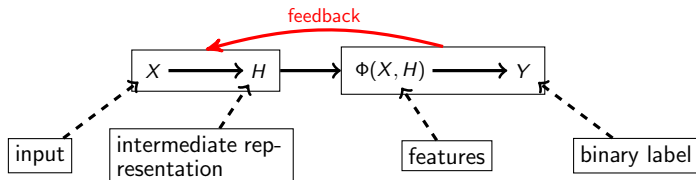
- **Property 1:** Jointly learn intermediate representations and labels



- **Find an intermediate representation that helps the binary task**

Learning Constrained Latent Representation (LCLR)

- **Property 1:** Jointly learn intermediate representations and labels



- **Find an intermediate representation that helps the binary task**

Property 2: Constraint-based inference for the intermediate representation

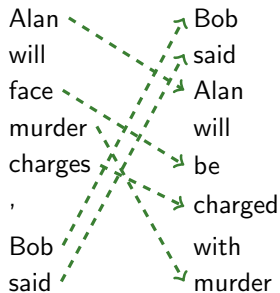
- Uses integer linear programming on latent variables
- Easy to inject constraints on *latent variables*
- Easy to generalize to other tasks

- 1 Motivation and Contribution
- 2 Property 1: Jointly learn intermediate representations and labels
- 3 Property 2: Constraint-based inference for the intermediate representation
- 4 LCLR: Putting Everything Together
- 5 Experiments

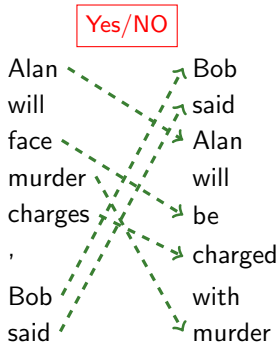
- 1 Motivation and Contribution
- 2 **Property 1: Jointly learn intermediate representations and labels**
- 3 Property 2: Constraint-based inference for the intermediate representation
- 4 LCLR: Putting Everything Together
- 5 Experiments

The intuition behind the joint approach

Yes/NO



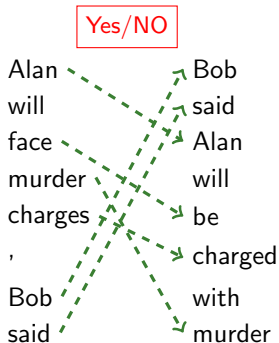
The intuition behind the joint approach



intermediate representation $\Leftrightarrow \{1, -1\}$

- Only positive examples have good intermediate representations
- **No** negative example has a good intermediate representation

The intuition behind the joint approach



intermediate representation $\Leftrightarrow \{1, -1\}$

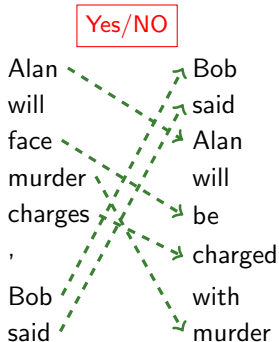
- Only positive examples have good intermediate representations
- **No** negative example has a good intermediate representation

\mathbf{x} : a sentence pair

h : an alignment between two sentences

$\mathcal{H}(\mathbf{x})$: all possible alignments for \mathbf{x}

The intuition behind the joint approach



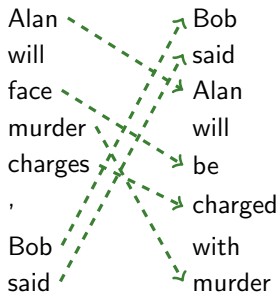
intermediate representation $\Leftrightarrow \{1, -1\}$

- Only positive examples have good intermediate representations
- **No** negative example has a good intermediate representation

\mathbf{x} : a sentence pair, **weight vector**: \mathbf{u}
 h : an alignment between two sentences
 $\mathcal{H}(\mathbf{x})$: all possible alignments for \mathbf{x}

The intuition behind the joint approach

Yes/NO



intermediate representation $\Leftrightarrow \{1, -1\}$

- Only positive examples have good intermediate representations
- **No** negative example has a good intermediate representation

\mathbf{x} : a sentence pair, **weight vector**: \mathbf{u}
 h : an alignment between two sentences
 $\mathcal{H}(\mathbf{x})$: all possible alignments for \mathbf{x}

- Pair \mathbf{x}_1 is positive
 - There must exist a good explanation that justifies the positive label
 - $\exists \mathbf{h}, \mathbf{u}^T \Phi(\mathbf{x}_1, \mathbf{h}) \geq 0$
- Pair \mathbf{x}_2 is negative
 - No explanation is good enough to justify the positive label
 - $\forall \mathbf{h}, \mathbf{u}^T \Phi(\mathbf{x}_2, \mathbf{h}) \leq 0$

Geometric interpretation: the case of two examples

- Pair x_1 is positive
 - There must exist a good explanation that justifies the positive label
 - $\exists \mathbf{h}, \mathbf{u}^T \Phi(\mathbf{x}_1, \mathbf{h}) \geq 0$, or $\max_{\mathbf{h}} \mathbf{u}^T \Phi(\mathbf{x}_1, \mathbf{h}) \geq 0$
- Pair x_2 is negative
 - No explanation is good enough to justify the positive label
 - $\forall \mathbf{h}, \mathbf{u}^T \Phi(\mathbf{x}_2, \mathbf{h}) \leq 0$, or $\max_{\mathbf{h}} \mathbf{u}^T \Phi(\mathbf{x}_2, \mathbf{h}) \leq 0$

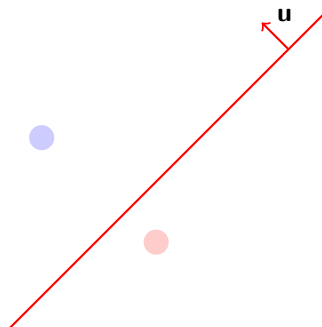
Geometric interpretation: the case of two examples

- Pair \mathbf{x}_1 is positive
 - There must exist a good explanation that justifies the positive label
 - $\exists \mathbf{h}, \mathbf{u}^T \Phi(\mathbf{x}_1, \mathbf{h}) \geq 0$, or $\max_{\mathbf{h}} \mathbf{u}^T \Phi(\mathbf{x}_1, \mathbf{h}) \geq 0$
- Pair \mathbf{x}_2 is negative
 - No explanation is good enough to justify the positive label
 - $\forall \mathbf{h}, \mathbf{u}^T \Phi(\mathbf{x}_2, \mathbf{h}) \leq 0$, or $\max_{\mathbf{h}} \mathbf{u}^T \Phi(\mathbf{x}_2, \mathbf{h}) \leq 0$



Geometric interpretation: the case of two examples

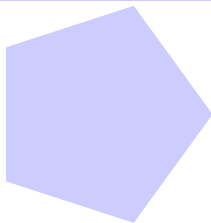
- Pair x_1 is positive
 - There must exist a good explanation that justifies the positive label
 - $\exists \mathbf{h}, \mathbf{u}^T \Phi(\mathbf{x}_1, \mathbf{h}) \geq 0$, or $\max_{\mathbf{h}} \mathbf{u}^T \Phi(\mathbf{x}_1, \mathbf{h}) \geq 0$
- Pair x_2 is negative
 - No explanation is good enough to justify the positive label
 - $\forall \mathbf{h}, \mathbf{u}^T \Phi(\mathbf{x}_2, \mathbf{h}) \leq 0$, or $\max_{\mathbf{h}} \mathbf{u}^T \Phi(\mathbf{x}_2, \mathbf{h}) \leq 0$



Geometric interpretation: the case of two examples

- Pair \mathbf{x}_1 is positive
 - There must exist a good explanation that justifies the positive label
 - $\exists \mathbf{h}, \mathbf{u}^T \Phi(\mathbf{x}_1, \mathbf{h}) \geq 0$, or $\max_{\mathbf{h}} \mathbf{u}^T \Phi(\mathbf{x}_1, \mathbf{h}) \geq 0$
- Pair \mathbf{x}_2 is negative
 - No explanation is good enough to justify the positive label
 - $\forall \mathbf{h}, \mathbf{u}^T \Phi(\mathbf{x}_2, \mathbf{h}) \leq 0$, or $\max_{\mathbf{h}} \mathbf{u}^T \Phi(\mathbf{x}_2, \mathbf{h}) \leq 0$

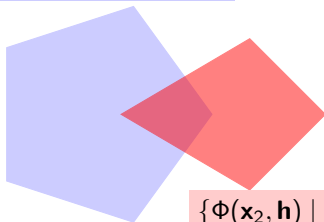
$$\{\Phi(\mathbf{x}_1, \mathbf{h}) \mid \mathbf{h} \in \mathcal{H}(\mathbf{x}_1)\}$$



Geometric interpretation: the case of two examples

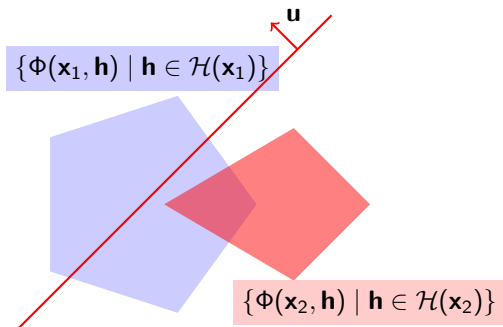
- Pair \mathbf{x}_1 is positive
 - There must exist a good explanation that justifies the positive label
 - $\exists \mathbf{h}, \mathbf{u}^T \Phi(\mathbf{x}_1, \mathbf{h}) \geq 0$, or $\max_{\mathbf{h}} \mathbf{u}^T \Phi(\mathbf{x}_1, \mathbf{h}) \geq 0$
- Pair \mathbf{x}_2 is negative
 - No explanation is good enough to justify the positive label
 - $\forall \mathbf{h}, \mathbf{u}^T \Phi(\mathbf{x}_2, \mathbf{h}) \leq 0$, or $\max_{\mathbf{h}} \mathbf{u}^T \Phi(\mathbf{x}_2, \mathbf{h}) \leq 0$

$$\{\Phi(\mathbf{x}_1, \mathbf{h}) \mid \mathbf{h} \in \mathcal{H}(\mathbf{x}_1)\}$$



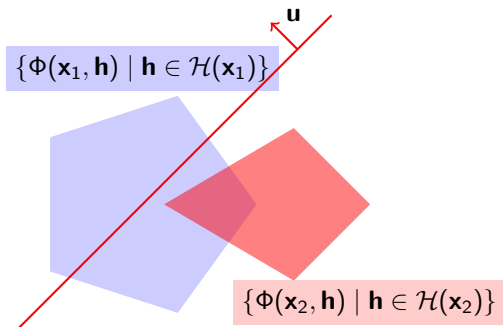
Geometric interpretation: the case of two examples

- Pair \mathbf{x}_1 is positive
 - There must exist a good explanation that justifies the positive label
 - $\exists \mathbf{h}, \mathbf{u}^T \Phi(\mathbf{x}_1, \mathbf{h}) \geq 0$, or $\max_{\mathbf{h}} \mathbf{u}^T \Phi(\mathbf{x}_1, \mathbf{h}) \geq 0$
- Pair \mathbf{x}_2 is negative
 - No explanation is good enough to justify the positive label
 - $\forall \mathbf{h}, \mathbf{u}^T \Phi(\mathbf{x}_2, \mathbf{h}) \leq 0$, or $\max_{\mathbf{h}} \mathbf{u}^T \Phi(\mathbf{x}_2, \mathbf{h}) \leq 0$



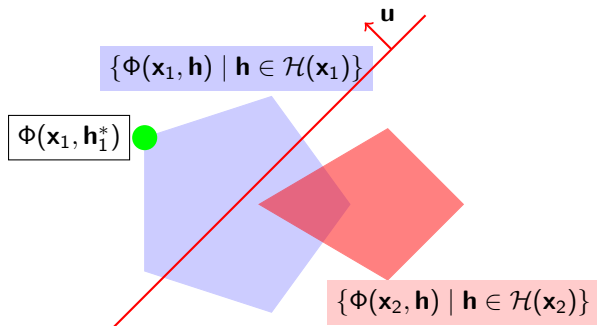
Geometric interpretation: the case of two examples

- Pair \mathbf{x}_1 is positive
 - There must exist a good explanation that justifies the positive label
 - $\exists \mathbf{h}, \mathbf{u}^T \Phi(\mathbf{x}_1, \mathbf{h}) \geq 0$, or $\max_{\mathbf{h}} \mathbf{u}^T \Phi(\mathbf{x}_1, \mathbf{h}) \geq 0$
- Pair \mathbf{x}_2 is negative
 - No explanation is good enough to justify the positive label
 - $\forall \mathbf{h}, \mathbf{u}^T \Phi(\mathbf{x}_2, \mathbf{h}) \leq 0$, or $\max_{\mathbf{h}} \mathbf{u}^T \Phi(\mathbf{x}_2, \mathbf{h}) \leq 0$



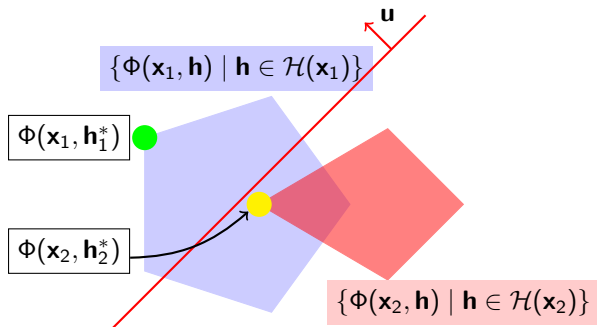
Geometric interpretation: the case of two examples

- Pair \mathbf{x}_1 is positive
 - There must exist a good explanation that justifies the positive label
 - $\exists \mathbf{h}, \mathbf{u}^T \Phi(\mathbf{x}_1, \mathbf{h}) \geq 0$, or $\max_{\mathbf{h}} \mathbf{u}^T \Phi(\mathbf{x}_1, \mathbf{h}) \geq 0$
- Pair \mathbf{x}_2 is negative
 - No explanation is good enough to justify the positive label
 - $\forall \mathbf{h}, \mathbf{u}^T \Phi(\mathbf{x}_2, \mathbf{h}) \leq 0$, or $\max_{\mathbf{h}} \mathbf{u}^T \Phi(\mathbf{x}_2, \mathbf{h}) \leq 0$



Geometric interpretation: the case of two examples

- Pair x_1 is positive
 - There must exist a good explanation that justifies the positive label
 - $\exists \mathbf{h}, \mathbf{u}^T \Phi(\mathbf{x}_1, \mathbf{h}) \geq 0$, or $\max_{\mathbf{h}} \mathbf{u}^T \Phi(\mathbf{x}_1, \mathbf{h}) \geq 0$
- Pair x_2 is negative
 - No explanation is good enough to justify the positive label
 - $\forall \mathbf{h}, \mathbf{u}^T \Phi(\mathbf{x}_2, \mathbf{h}) \leq 0$, or $\max_{\mathbf{h}} \mathbf{u}^T \Phi(\mathbf{x}_2, \mathbf{h}) \leq 0$

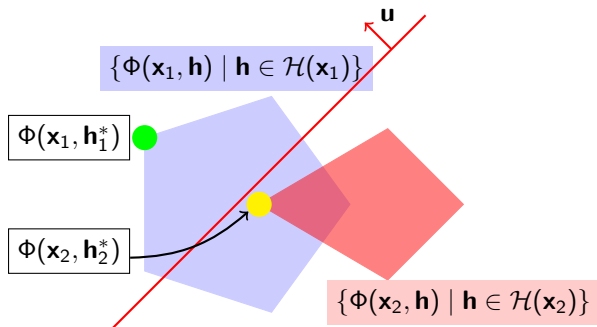


Geometric interpretation: the case of two examples

- Pair x_1 is positive
 - There must exist a good explanation that justifies the positive label
 - $\exists \mathbf{h}, \mathbf{u}^T \Phi(\mathbf{x}_1, \mathbf{h}) \geq 0$, or $\max_{\mathbf{h}} \mathbf{u}^T \Phi(\mathbf{x}_1, \mathbf{h}) \geq 0$
- Pair x_2 is negative
 - No explanation is good enough to justify the positive label
 - $\forall \mathbf{h}, \mathbf{u}^T \Phi(\mathbf{x}_2, \mathbf{h}) \leq 0$, or $\max_{\mathbf{h}} \mathbf{u}^T \Phi(\mathbf{x}_2, \mathbf{h}) \leq 0$

- The prediction function:

$$\max_{\mathbf{h}} \mathbf{u}^T \Phi(\mathbf{x}, \mathbf{h})$$



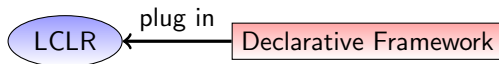
- ① Motivation and Contribution
- ② Property 1: Jointly learn intermediate representations and labels
- ③ Property 2: Constraint-based inference for the intermediate representation
- ④ LCLR: Putting Everything Together
- ⑤ Experiments

Declarative Framework

- Why is a declarative framework important?
 - No more custom-designed inference procedures
 - Easy to generalize to other tasks
 - Easy to inject constraints and linguistic intuition

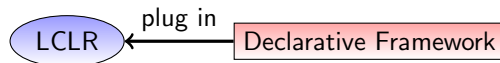
Declarative Framework

- Why is a declarative framework important?
 - No more custom-designed inference procedures
 - Easy to generalize to other tasks
 - Easy to inject constraints and linguistic intuition



Declarative Framework

- Why is a declarative framework important?
 - No more custom-designed inference procedures
 - Easy to generalize to other tasks
 - Easy to inject constraints and linguistic intuition



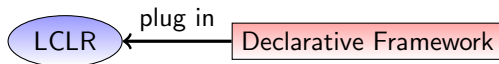
Paraphrasing

Model input as graphs. G_a : the first sentence. G_b : the second sentence.

- Each vertex in G_a can be mapped to at most one vertex in G_b (vice versa)
- Each edge in G_a can be mapped to at most one edge in G_b (vice versa)
- Edge mapping is active iff the corresponding node mappings are active

Declarative Framework

- Why is a declarative framework important?
 - No more custom-designed inference procedures
 - Easy to generalize to other tasks
 - Easy to inject constraints and linguistic intuition
 - **Check out the CCM tutorial!**



Paraphrasing

Model input as graphs. G_a : the first sentence. G_b : the second sentence.

- Each vertex in G_a can be mapped to at most one vertex in G_b (vice versa)
- Each edge in G_a can be mapped to at most one edge in G_b (vice versa)
- Edge mapping is active iff the corresponding node mappings are active

Finding intermediate representation using ILP

Sentence 1

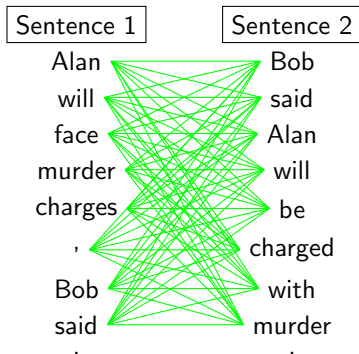
Alan
will
face
murder
charges
,
Bob
said
.

Sentence 2

Bob
said
Alan
will
be
charged
with
murder
.

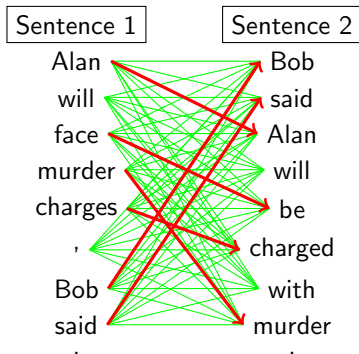
- **We need this because of the formulation. You do not need to parse the symbols in this page**

Finding intermediate representation using ILP



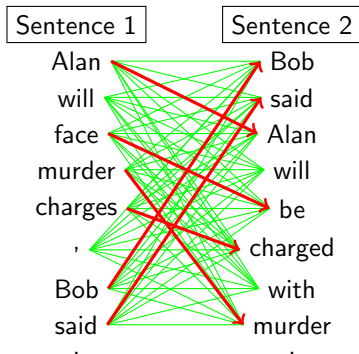
- **We need this because of the formulation. You do not need to parse the symbols in this page**
- $\Gamma(x)$, the set of all “parts” that x can generate **$|\Gamma(x)| = 8 \times 8 = 64$**

Finding intermediate representation using ILP



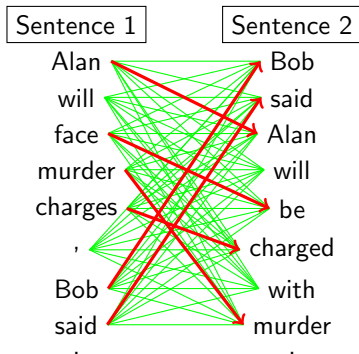
- **We need this because of the formulation. You do not need to parse the symbols in this page**
- $\Gamma(x)$, the set of all “parts” that x can generate $|\Gamma(x)| = 8 \times 8 = 64$
- Rewrite $\mathbf{h} \in \{0, 1\}^{64}$ as a binary vector $\mathbf{h} = \{0, 0, 0, \dots, 1, 0, 0, 1, 1\}$

Finding intermediate representation using ILP



- **We need this because of the formulation. You do not need to parse the symbols in this page**
- $\Gamma(x)$, the set of all “parts” that x can generate $|\Gamma(x)| = 8 \times 8 = 64$
- Rewrite $\mathbf{h} \in \{0, 1\}^{64}$ as a binary vector $\mathbf{h} = \{0, 0, 0, \dots, 1, 0, 0, 1, 1\}$
- A feature vector $\Phi_s(x)$ for every part h_s

Finding intermediate representation using ILP



- **We need this because of the formulation. You do not need to parse the symbols in this page**
- $\Gamma(x)$, the set of all “parts” that x can generate $|\Gamma(x)| = 8 \times 8 = 64$
- Rewrite $\mathbf{h} \in \{0, 1\}^{64}$ as a binary vector $\mathbf{h} = \{0, 0, 0, \dots, 1, 0, 0, 1, 1\}$
- A feature vector $\Phi_s(x)$ for every part h_s

Inference Problem = ILP formulation (pink box)

$$\max_{\mathbf{h} \in \mathcal{H}} \mathbf{u}^T \Phi(\mathbf{x}, \mathbf{h}) = \max_{\mathbf{h} \in \mathcal{H}} \mathbf{u}^T \sum_{s \in \Gamma(\mathbf{x})} h_s \Phi_s(\mathbf{x})$$

- 1 Motivation and Contribution
- 2 Property 1: Jointly learn intermediate representations and labels
- 3 Property 2: Constraint-based inference for the intermediate representation
- 4 LCLR: Putting Everything Together**
- 5 Experiments

LCLR: The objective function

- **Review:** Logistic Regression and Support Vector Machine
 - Decision Function: $f(\mathbf{x}, \mathbf{u}) \geq 0$

LCLR: The objective function

- **Review:** Logistic Regression and Support Vector Machine
 - Decision Function: $f(\mathbf{x}, \mathbf{u}) \geq 0$
 - Objective Function:

$$\min_{\mathbf{u}} \frac{1}{2} \|\mathbf{u}\|^2 + C \sum_{i=1}^l \ell(-y_i f(\mathbf{x}, \mathbf{u}))$$

LCLR: The objective function

- **Review:** Logistic Regression and Support Vector Machine
 - Decision Function: $\mathbf{u}^T \Phi(\mathbf{x}) \geq 0$
 - Objective Function:

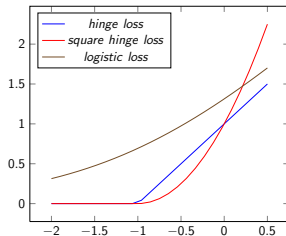
$$\min_{\mathbf{u}} \frac{1}{2} \|\mathbf{u}\|^2 + C \sum_{i=1}^l \ell(-y_i \mathbf{u}^T \Phi(\mathbf{x}_i))$$

LCLR: The objective function

- **Review:** Logistic Regression and Support Vector Machine

- Decision Function: $\mathbf{u}^T \Phi(\mathbf{x}) \geq 0$
- Objective Function:

$$\min_{\mathbf{u}} \frac{1}{2} \|\mathbf{u}\|^2 + C \sum_{i=1}^l \ell(-y_i \mathbf{u}^T \Phi(\mathbf{x}_i))$$



LCLR: The objective function

- Learning over **C**onstrained **L**atent **R**epresentations
 - Decision Function (**ILP**): $f(\mathbf{x}, \mathbf{u}) \geq 0$

LCLR: The objective function

- Learning over **C**onstrained **L**atent **R**epresentations
 - Decision Function (**ILP**): $f(\mathbf{x}, \mathbf{u}) \geq 0$
 - Objective Function

$$\min_{\mathbf{u}} \frac{1}{2} \|\mathbf{u}\|^2 + C \sum_{i=1}^l \ell(-y_i f(\mathbf{x}, \mathbf{u}))$$

LCLR: The objective function

- Learning over **C**onstrained **L**atent **R**epresentations

- Decision Function (**ILP**): $\max_{\mathbf{h} \in \mathcal{H}} \mathbf{u}^T \sum_{s \in \Gamma(\mathbf{x})} h_s \Phi_s(\mathbf{x}) \geq 0$
- Objective Function

$$\min_{\mathbf{u}} \frac{1}{2} \|\mathbf{u}\|^2 + C \sum_{i=1}^l \ell(-y_i \max_{\mathbf{h} \in \mathcal{H}} \mathbf{u}^T \sum_{s \in \Gamma(\mathbf{x})} h_s \Phi_s(\mathbf{x}))$$

LCLR: The objective function

- Learning over **C**onstrained **L**atent **R**epresentations

- Decision Function (**ILP**): $\max_{\mathbf{h} \in \mathcal{H}} \mathbf{u}^T \sum_{s \in \Gamma(\mathbf{x})} h_s \Phi_s(\mathbf{x}) \geq 0$
- Objective Function

$$\min_{\mathbf{u}} \frac{1}{2} \|\mathbf{u}\|^2 + C \sum_{i=1}^l \ell(-y_i \max_{\mathbf{h} \in \mathcal{H}} \mathbf{u}^T \sum_{s \in \Gamma(\mathbf{x})} h_s \Phi_s(\mathbf{x}))$$

Beyond standard LR/SVM

Solves an inference problem (max) to select \mathbf{h} (also affect features)

Challenges in optimizing the objective function

$$\min_{\mathbf{u}} \frac{1}{2} \|\mathbf{u}\|^2 + C \sum_{i=1}^l \ell(-y_i \max_{\mathbf{h} \in \mathcal{H}} \mathbf{u}^T \sum_{s \in \Gamma(\mathbf{x})} h_s \Phi_s(\mathbf{x}))$$

Not a regular LR/SVM

- LCLR has an inference procedure inside the minimization problem

Challenges in optimizing the objective function

$$\min_{\mathbf{u}} \frac{1}{2} \|\mathbf{u}\|^2 + C \sum_{i=1}^l \ell(-y_i \max_{\mathbf{h} \in \mathcal{H}} \mathbf{u}^T \sum_{s \in \Gamma(\mathbf{x})} h_s \Phi_s(\mathbf{x}))$$

Not a regular LR/SVM

- LCLR has an inference procedure inside the minimization problem

No shortcut

- Find the best representation for all examples
- Obtain a new weight vector using a LR/SVM package with the updated representations.
- Repeat.

Challenges in optimizing the objective function

$$\min_{\mathbf{u}} \frac{1}{2} \|\mathbf{u}\|^2 + C \sum_{i=1}^l \ell(-y_i \max_{\mathbf{h} \in \mathcal{H}} \mathbf{u}^T \sum_{s \in \Gamma(\mathbf{x})} h_s \Phi_s(\mathbf{x}))$$

Not a regular LR/SVM

- LCLR has an inference procedure inside the minimization problem

No shortcut

- Find the best representation for all examples
- Obtain a new weight vector using a LR/SVM package with the updated representations.
- Repeat.

Does not minimize the objective function

Algorithm

- 1: Find the best intermediate representations for **positive examples**
- 2: Find the weight vector with this intermediate representation
 - Still need to do inference for negative examples
 - **Not a regular SVM problem even in this step!**
- 3: Repeat!

Algorithm

- 1: Find the best intermediate representations for **positive examples**
- 2: Find the weight vector with this intermediate representation
 - Still need to do inference for negative examples
 - **Not a regular SVM problem even in this step!**
- 3: Repeat!

This algorithm converges when ℓ is monotonically increasing and convex.

LCLR: optimization procedure

Algorithm

- 1: Find the best intermediate representations for **positive examples**
- 2: Find the weight vector with this intermediate representation
 - Still need to do inference for negative examples
 - **Not a regular SVM problem even in this step!**
- 3: Repeat!

This algorithm converges when ℓ is monotonically increasing and convex.

Properties of the algorithm: Asymmetric nature

- Asymmetry between positive and negative examples
- Converting a non-convex problem into a series of smaller convex problems

Comparison to other latent variable frameworks

Inference procedure

- Other frameworks often use application-specific inference.
- LCLR allows you to add constraints and generalize to other tasks.

Comparison to other latent variable frameworks

Inference procedure

- Other frameworks often use application-specific inference.
- LCLR allows you to add constraints and generalize to other tasks.

Learning

- Not only for SVM. Many different loss functions can be used.
- Dual coordinate descent methods and cutting plane method
 - Fewer parameters to tune. Allows parallel inference procedure.

Comparison to other latent variable frameworks

Inference procedure

- Other frameworks often use application-specific inference.
- LCLR allows you to add constraints and generalize to other tasks.

Learning

- Not only for SVM. Many different loss functions can be used.
- Dual coordinate descent methods and cutting plane method
 - Fewer parameters to tune. Allows parallel inference procedure.

CRF-like latent variable framework

- LCLR can use logistic regression and have a probabilistic interpretation
- LCLR solves the “max” problem. CRF-like models solves the “sum” problem. **“Max” enables adding constraints.** [▶ Jump](#)

Outline

- ① Motivation and Contribution
- ② Property 1: Jointly learn intermediate representations and labels
- ③ Property 2: Constraint-based inference for the intermediate representation
- ④ LCLR: Putting Everything Together
- ⑤ Experiments

Experimental setting

Tasks

- Transliteration: Is named entity B a transliteration of A?
- Textual Entailment: Can sentence A entail sentence B?
- Paraphrase Identification

Goal of experiments

- Determine if a joint approach be better than a two-stage approach?

Two-stage approach versus LCLR

- Exactly **the same** features and definition of latent structures
 - Our two-stage approach uses a domain-dependent heuristic to find an intermediate representation
 - LCLR finds the intermediate representation automatically
- Initialization of LCLR: two-stage

Experimental results

| Transliteration System | Joint | ILP | Acc | MRR |
|----------------------------|-------|-----|-----|-----|
| (Goldwasser and Roth 2008) | * | | | |
| Our two-stage | | * | | |
| Our LCLR | * | * | | |

Experimental results

| Transliteration System | Joint | ILP | Acc | MRR |
|----------------------------|-------|-----|-----|------|
| (Goldwasser and Roth 2008) | * | | N/A | 89.4 |
| Our two-stage | | * | | |
| Our LCLR | * | * | | |

Experimental results

| Transliteration System | Joint | ILP | Acc | MRR |
|----------------------------|-------|-----|------|------|
| (Goldwasser and Roth 2008) | * | | N/A | 89.4 |
| Our two-stage | | * | 80.0 | 85.7 |
| Our LCLR | * | * | | |

Experimental results

| Transliteration System | Joint | ILP | Acc | MRR |
|----------------------------|-------|-----|-------------|-------------|
| (Goldwasser and Roth 2008) | * | | N/A | 89.4 |
| Our two-stage | | * | 80.0 | 85.7 |
| Our LCLR | * | * | 92.3 | 95.4 |

Experimental results

| Transliteration System | Joint | ILP | Acc | MRR |
|----------------------------|-------|-----|-------------|-------------|
| (Goldwasser and Roth 2008) | * | | N/A | 89.4 |
| Our two-stage | | * | 80.0 | 85.7 |
| Our LCLR | * | * | 92.3 | 95.4 |

| Entailment System | Joint | ILP | Acc |
|----------------------------|-------|-----|-----|
| Median of TAC 2009 systems | | | |
| Our two-stage | | * | |
| Our LCLR | * | * | |

Experimental results

| Transliteration System | Joint | ILP | Acc | MRR |
|-------------------------------|-------|-----|-------------|-------------|
| (Goldwasser and Roth 2008) | * | | N/A | 89.4 |
| Our two-stage | | * | 80.0 | 85.7 |
| Our LCLR | * | * | 92.3 | 95.4 |

| Entailment System | Joint | ILP | Acc |
|----------------------------|-------|-----|------------|
| Median of TAC 2009 systems | | | 61.5 |
| Our two-stage | | * | |
| Our LCLR | * | * | |

Experimental results

| Transliteration System | Joint | ILP | Acc | MRR |
|----------------------------|-------|-----|-------------|-------------|
| (Goldwasser and Roth 2008) | * | | N/A | 89.4 |
| Our two-stage | | * | 80.0 | 85.7 |
| Our LCLR | * | * | 92.3 | 95.4 |

| Entailment System | Joint | ILP | Acc |
|----------------------------|-------|-----|------|
| Median of TAC 2009 systems | | | 61.5 |
| Our two-stage | | * | 65.0 |
| Our LCLR | * | * | |

Experimental results

| Transliteration System | Joint | ILP | Acc | MRR |
|----------------------------|-------|-----|-------------|-------------|
| (Goldwasser and Roth 2008) | * | | N/A | 89.4 |
| Our two-stage | | * | 80.0 | 85.7 |
| Our LCLR | * | * | 92.3 | 95.4 |

| Entailment System | Joint | ILP | Acc |
|----------------------------|-------|-----|-------------|
| Median of TAC 2009 systems | | | 61.5 |
| Our two-stage | | * | 65.0 |
| Our LCLR | * | * | 66.8 |

Paraphrase Identification

| Paraphrase System | Joint | ILP | Acc |
|--|-------|-----|-------|
| <i>Experiments using (Dolan, Quirk, and Brockett 2004)</i> | | | |
| (Qiu, Kan, and Chua 2006) | | | 72.00 |
| (Das and Smith 2009) | * | | 73.86 |
| (Wan, Dras, Dale, and Paris 2006) | | | 75.60 |
| Our two-stage | | * | |
| Our LCLR | * | * | |

Paraphrase Identification

| Paraphrase System | Joint | ILP | Acc |
|--|-------|-----|--------------|
| <i>Experiments using (Dolan, Quirk, and Brockett 2004)</i> | | | |
| (Qiu, Kan, and Chua 2006) | | | 72.00 |
| (Das and Smith 2009) | * | | 73.86 |
| (Wan, Dras, Dale, and Paris 2006) | | | 75.60 |
| Our two-stage | | * | 76.23 |
| Our LCLR | * | * | 76.41 |

Paraphrase Identification

| Paraphrase System | Joint | ILP | Acc |
|--|-------|-----|--------------|
| <i>Experiments using (Dolan, Quirk, and Brockett 2004)</i> | | | |
| (Qiu, Kan, and Chua 2006) | | | 72.00 |
| (Das and Smith 2009) | * | | 73.86 |
| (Wan, Dras, Dale, and Paris 2006) | | | 75.60 |
| Our two-stage | | * | 76.23 |
| Our LCLR | * | * | 76.41 |
| <i>Experiments using Noisy data set</i> | | | |
| Our two-stage | | * | |
| Our LCLR | * | * | |

Paraphrase Identification

| Paraphrase System | Joint | ILP | Acc |
|--|-------|-----|--------------|
| <i>Experiments using (Dolan, Quirk, and Brockett 2004)</i> | | | |
| (Qiu, Kan, and Chua 2006) | | | 72.00 |
| (Das and Smith 2009) | * | | 73.86 |
| (Wan, Dras, Dale, and Paris 2006) | | | 75.60 |
| Our two-stage | | * | 76.23 |
| Our LCLR | * | * | 76.41 |
| <i>Experiments using Noisy data set</i> | | | |
| Our two-stage | | * | 72.00 |
| Our LCLR | * | * | 72.75 |

Conclusions

$$\text{LCLR} = \text{Constraint-based Inference} + \text{Large Margin Learning}$$

Contributions

- LCLR joint approach is better than two-stage approaches
- LCLR allows the use of constraints on latent variables
- A novel learning framework

Conclusions

$$\text{LCLR} = \text{Constraint-based Inference} + \text{Large Margin Learning}$$

Contributions

- LCLR joint approach is better than two-stage approaches
- LCLR allows the use of constraints on latent variables
- A novel learning framework

Bonus: Learning Structures with Indirect Supervision

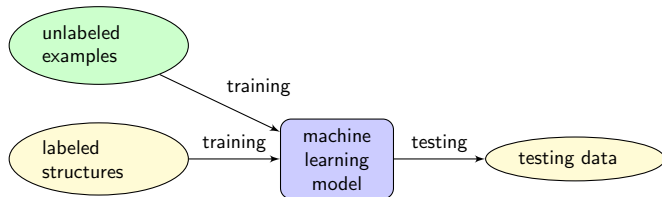
- Easy to get **binary** labeled data can be used to improve learning **structures!**
- Check out our ICML paper this year!

Thank you!

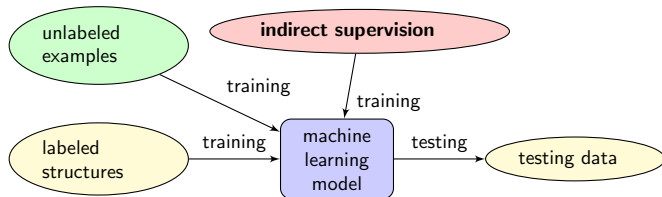


- Our learning code is available: the **JLIS** package
- <http://l2r.cs.uiuc.edu/~cogcomp/software.php>

Main Idea: Learning with indirect supervision

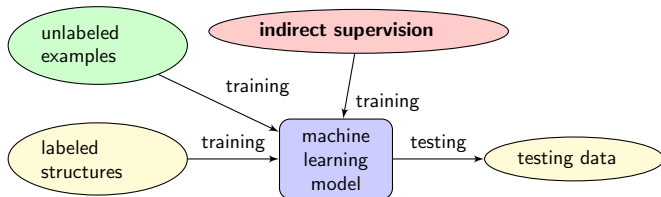


Main Idea: Learning with indirect supervision



Indirect supervision: the supervision form that does not tell you the target output directly

Main Idea: Learning with indirect supervision

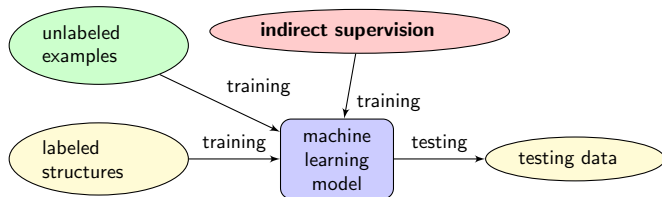


Indirect supervision: the supervision form that does not tell you the target output directly

Advantage of using indirect supervision

- Can directly use human/domain knowledge to improve the model
- Allow us to use supervision signals that are a lot easier to obtain than labeling structures
- Use *existing* labeled data for the related tasks

Main Idea: Learning with indirect supervision



Indirect supervision: the supervision form that does not tell you the target output directly

Advantage of using indirect supervision

- Can directly use human/domain knowledge to improve the model
- Allow us to use supervision signals that are a lot easier to obtain than labeling structures
- Use *existing* labeled data for the related tasks

Indirect supervision greatly reduce the supervision effort!

Compared to CRF-like latent variable framework

CRF-like latent variable framework

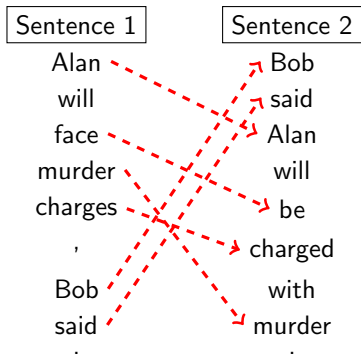
$$P(y = 1|\mathbf{x}) = \sum_{\mathbf{h}} P(y = 1, \mathbf{h}|\mathbf{x}) = \frac{\sum_{\mathbf{h}} \exp(\mathbf{u}^T \phi(\mathbf{x}, \mathbf{h}, y = 1))}{\sum_{\mathbf{h}, y} \exp(\mathbf{u}^T \phi(\mathbf{x}, \mathbf{h}, y))}$$

LCLR with logistic loss

$$P(y = 1|\mathbf{x}) = \frac{\max_{\mathbf{h}} \exp(\mathbf{u}^T \phi(\mathbf{x}, \mathbf{h}))}{1 + \max_{\mathbf{h}} \exp(\mathbf{u}^T \phi(\mathbf{x}, \mathbf{h}))}$$

- Difference 1: LCLR only models the “goodness”
 - This is important for many NLP problems, where only positive examples have good representations.
- Difference 2: LCLR only need to solve the max inference
 - Sometimes calculating sum is a lot harder!!
- [▶ Jump back](#)






Paraphrase Identification: Revisited



- **Left:** The intermediate representation is not expressive enough
 - For example, “word ordering” is a problem
- The real setting
 - Input: two word sequence \rightarrow two graphs.
 - We used Stanford Parser to construct dependency parse trees for each sentence

Integer Linear Programming to solve the graph matching problem

- Four types of sub-structure: node matching, node-deletion, edge matching, edge-deletion
- Add constraints to enforce consistency
 - edge matching if and only if the corresponding nodes are matched

-  Dagan, I., O. Glickman, and B. Magnini (Eds.) (2006).
The PASCAL Recognising Textual Entailment Challenge.
-  Das, D. and N. A. Smith (2009).
Paraphrase identification as probabilistic quasi-synchronous recognition.
In *ACL*.
-  Dolan, W., C. Quirk, and C. Brockett (2004).
Unsupervised construction of large paraphrase corpora: Exploiting massively parallel news sources.
In *COLING*.
-  Goldwasser, D. and D. Roth (2008).
Active sample selection for named entity transliteration.
In *ACL*.
Short Paper.
-  Klementiev, A. and D. Roth (2008).
Named entity transliteration and discovery in multilingual corpora.
In C. Goutte, N. Cancedda, M. Dymetman, and G. Foster (Eds.),
Learning Machine Translation.



Qiu, L., M.-Y. Kan, and T.-S. Chua (2006).

Paraphrase recognition via dissimilarity significance classification.
In *EMNLP*.



Wan, S., M. Dras, R. Dale, and C. Paris (2006).

Using dependency-based features to take the para-farceöut of
paraphrase.
In *Proc. of the Australasian Language Technology Workshop
(ALTW)*.