Logic-based Architectures

Neuro-symbolic modeling



What we have seen so far: Logic to design loss functions

Most neural networks are opaque and the only interfaces we have are at the inputs and outputs

This means that most constraints will also about them

Can we write loss functions about the outputs that encourage the model to satisfy the constraints? Each constraint will be mapped to its own loss

We can then use any learning algorithm/optimizer

This lecture: Logic to design networks

Suppose we have a neural network and a constraint that involves a few nodes in the network

Can we somehow re-architect the network so that the resulting architecture (by construction) satisfies the constraint? Or almost satisfies the constraint?

Lecture outline

- Conjunctions, Disjunctions and Boolean functions as threshold networks
- The McCulloch-Pitts paper
- Knowledge-Based Artificial Neural Networks
- Augmenting neural networks with logic

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This function is equivalent to the linear threshold unit $X_1 + X_2 \ge 2$

Easy to verify this.

The function is true if, and only if, both the variables are set to **true**. That is, the number of **true**'s (i.e. ones) in the summation is at least two

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And linear threshold units are one layer networks with a threshold activation $f_1 = \operatorname{sgn}(X_1 + X_2 - 2)$

Example 2: Consider the function

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$$f_2 = X_1 \land \neg X_2$$

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And linear threshold units are one layer networks with a threshold activation

$$f_3 = \operatorname{sgn}\left(\sum X_i - 1\right)$$

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And linear threshold units are one layer networks with a threshold activation $f_4 = \text{sgn}(-X_1 + X_2)$

This offers a simple recipe to write them as threshold linear units

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Suppose $f = l_1 \vee l_2 \vee \cdots$,

where l_i is the variable X_i or its negation $\neg X_i$

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But some literals show up with a negation. For such literals $l_i = 1 - X_i$

Literals that have positive polarity (i.e., not negated) $sgn\left(\sum_{i\in P} X_i - \sum_{i\in N} X_i + |N| - 1\right)$

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$$\operatorname{sgn}\left(\sum_{i\in P} X_i - \sum_{i\in N} X_i - |P|\right)$$

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How can we extend this to arbitrary Boolean functions?

Ideas?

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Any Boolean function can be written in as a conjunctive normal form

A conjunctive normal form is a conjunction of disjunctions

- We know how to write each disjunction as a one layer network
- Each disjunction produces a 0 or a 1
- The final function is a conjunction of these disjunction values. We know how to write the conjunction as a one layer network that operates on top of the disjunctions

Let's see an example

Arbitrary Boolean function as a two-layer network

An example

Consider $f = X_1 \rightarrow (X_2 \rightarrow X_3)$

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```
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$$(X_1 \lor X_3) \equiv \operatorname{sgn}(X_1 + X_3 - 1)$$



→ Edge weight = +1
Arbitrary Boolean function as a two-layer network

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Consider $f = X_1 \rightarrow (X_2 \rightarrow X_3)$

$\ln \text{CNF} (X_1 \lor X_3) \land (\neg X_1 \lor X_3)$

$$(X_1 \lor X_3) \equiv \operatorname{sgn}(X_1 + X_3 - 1)$$
$$(\neg X_1 \lor X_2) \equiv \operatorname{sgn}(-X_1 + X_2)$$





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- Threshold activations produce -1 or 1, but the construction we saw treats true and false as 1 and 0 respectively. Adapt the approach for -1 and +1
- 2. How will this construction change for a *disjunctive normal form*?
- 3. If any Boolean function can be represented as two layer network, what is the catch?

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The first paper to introduce artificial neural networks

BULLETIN OF MATHEMATICAL BIOPHYSICS VOLUME 5, 1943

A LOGICAL CALCULUS OF THE IDEAS IMMANENT IN NERVOUS ACTIVITY

WARREN S. MCCULLOCH AND WALTER PITTS

FROM THE UNIVERSITY OF ILLINOIS, COLLEGE OF MEDICINE, DEPARTMENT OF PSYCHIATRY AT THE ILLINOIS NEUROPSYCHIATRIC INSTITUTE, AND THE UNIVERSITY OF CHICAGO

"The method [...] does in fact provide a very convenient and workable procedure for constructing nervous nets to order..."

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Some examples:





 $N_{3}(t) = N_{1}(t-1) \land \neg N_{2}(t-1)$

 $N_{3}(t) = N_{1}(t-1) \vee \left(\neg N_{2}(t-2) \wedge N_{2}(t-3)\right)$

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$$N_3(t) = N_1(t-1) \land \neg N_2(t-1)$$



 $N_{3}(t) = N_{1}(t-1) \lor (\neg N_{2}(t-2) \land N_{2}(t-3))$ $N_{4}(t) = N_{2}(t-1) \land N_{2}(t-2)$

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This was an important paper

Introduced artificial neural networks

- Time plays an important role in the design of the networks
- Describes neural networks with loops as a mechanism to model memory

Showed that a network consisting of McCulloch-Pitts neurons can compute exactly those functions as a Turing machine with a finite tape

Influenced subsequent research into automata and logic. Some examples:

- John von Neumann's work on digital computers & theory of automata
- Stephen Kleene invented regular expressions in an attempt to describe a certain subset of McCulloch-Pitts neural networks (They used the term 'prehensible' to describe the sets)
- Perceptrons built on top of these ideas

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Suppose you want to teach a student to recognize members of a certain class

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Approach 1

Define a *domain theory* that describes:

- how to recognize critical facets of class members
- how those facets interact

Use this domain theory to teach the student to distinguish between members and nonmembers of the class

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Approach 2

Show the student many examples of objects, one at a time

 For each example, tell the student whether it is or is not a member of the class

After seeing sufficient examples, the student can identify new examples

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Hand-built classifiers

After seeing sufficient examples, the student can identify new examples

Empirical learning

Knowledge-Based Artificial Neural Networks (KBANN)

Towell, Geoffrey G., and Jude W. Shavlik. 1994. "Knowledge-Based Artificial Neural Networks." Artificial Intelligence 70 (1–2): 119–65

A hybrid that combines domain theories with learned systems

The high level approach:

- 1. Translate the domain rules into a neural network
- 2. Train the network using backpropagation

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Corresponde	ences	between	know	ledge-	bases and	neural	network	۲S.
		1.7		-				

Knowledge Base	Neural Network		
Final Conclusions	\Leftrightarrow	Output Units	
Supporting Facts	\iff	Input Units	
Intermediate Conclusions	\iff	Hidden Units	
Dependencies	\iff	Weighted Connections	

Converting knowledge bases into neural networks

At a high level, similar to what we have already seen

Works with a knowledge specified as Horn clauses



Translation of a conjunctive rule into a KBANN-net.

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Translation of disjunctive rules into a KBANN-net.



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This final network is ready to train on data

A more real example involving a genomics application



Key observations

When there's a limited amount of data, KBANN outperforms a knowledgeagnostic network

The approach constructs the structure of the network and assigns initial weights for some edges. Both factors are important

Limitation: Cannot handle rules that have cycles in them

The eventual learned network may overrule the initial weights that come from the rules. Yet the rules help empirically

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Is it realistic to build entire networks using logic?

What are some disadvantages?
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What are some disadvantages?

We may have an existing neural network architecture for a task

Don't want to get rid of something that works

The logical rules may be incomplete

- For complex phenomena, maybe there is no complete symbolic description

The logical rules may be incorrect

- Maybe they were derived using a theoretical framework that is not correct

The rules may be only partially correct

- Maybe they are to be treated as soft constraints that data should be allowed to override

Can we integrate rules into an existing network?

Not always possible

We will assume that some nodes in the network are *named neurons* (i.e. some nodes have externally defined semantics)

We will write rules about these nodes

Goal: Integrate rules into a network that can be trained end-to-end

Suppose we have a rule $Z \rightarrow Y$ and z and y are nodes in a neural network that correspond to these predicates

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Can we change something in the architecture that enforces this? Ideas?

The node z need not be directly connected to the node y

If z is 0, then the rule doesn't say anything about y







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Using differentiable rules

The solution: Relax the LHS with Lukasiewicz logic

AntecedentDistance $d(\mathbf{z})$ $\bigwedge_{i}^{i} Z_{i}$ $\max(0, \sum_{i} z_{i} - |Z| + 1)$ $\bigvee_{i}^{i} Z_{i}$ $\min(1, \sum_{i} z_{i})$ $\neg \bigvee_{i}^{i} Z_{i}$ $\max(0, 1 - \sum_{i} z_{i})$ $\neg \bigwedge_{i}^{i} Z_{i}$ $\min(1, N - \sum_{i} z_{i})$





 $A_1 \wedge A_2 \rightarrow B_1$



$$A_1 \land A_2 \to B_1$$

Step 1: LHS in Łukasiewicz logic $d(a_1, a_2) = \max(0, a_1 + a_2 - 1)$



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Step 2: Define constrained node: $b_1' = \sigma(\mathbf{w}^T \mathbf{x} + \rho \ d(a_1, a_2))$



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No additional trainable parameters introduced Hyperparameter ρ controls how strongly the constraint is enforced

Natural Language Inference

SNLI dataset, decomposable attention model [Parikh et al 2016]

Two constraints (formalized in first order logic):

- 1. If two words are related, they should be aligned
- 2. If no content word in the hypothesis is aligned, then the label cannot be Entail



1. Constraints help



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Difficulties with this approach

What are some shortcomings of the idea of constructing or editing neural network architectures with knowledge?

Difficulties with this approach

What are some shortcomings of the idea of constructing or editing neural network architectures with knowledge?

1. Acyclicity can be a strong constraint

2. Assumes that we have named neurons. Does not apply to modern transformer networks

Logic as architectures: Summary

- One of the oldest ideas in this area
 - Goes back to the original work of McCulloch & Pitts
- Key intuition: Generate or augment a neural network using rules
- Experiments show gains especially in low data regimes
- Design difficulties with modern large models