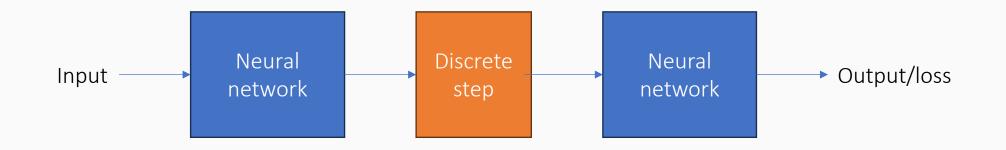
Learning with symbols within neural networks: Gumbel-Softmax

Neuro-symbolic modeling



Neural networks containing discrete elements



Let's see some examples

This lecture

- Motivating examples
- The straight-through estimator
- Gumbel-Softmax
- REINFORCE

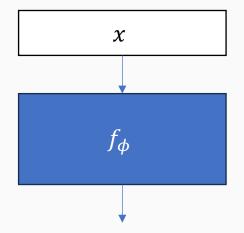
(others if time permits)

Not all these approaches are always applicable

Let us consider a simple neural network consisting of two sets of parameters ϕ and θ

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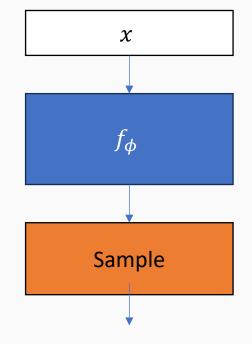
Given an example x, it computes $f_{\phi}(x)$ to produce a set of d scores



Let us consider a simple neural network consisting of two sets of parameters ϕ and θ

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A discrete value z is *sampled* from the normalized distribution associated with these scores

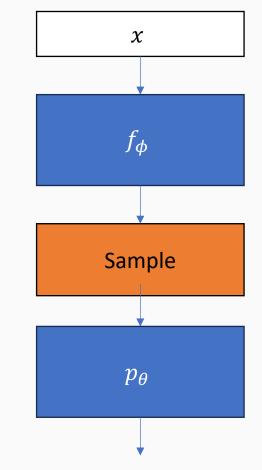


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The final output is then $g_{\theta}(z)$



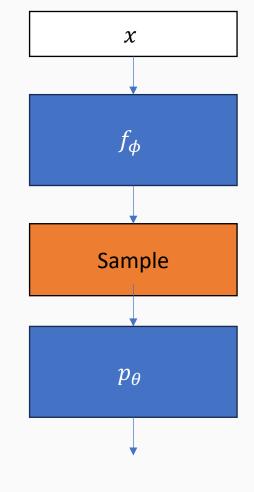
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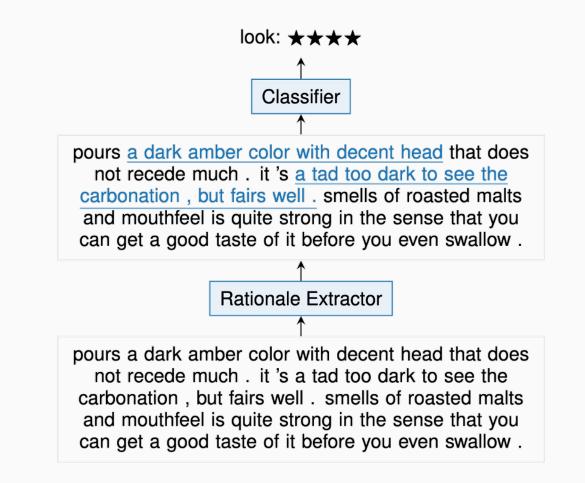
A discrete value z is sampled from the normalized distribution associated with these scores

The final output is then $g_{ heta}(z)$

By sampling z, we no longer have a differentiable link between the final output and the parameters θ



Example: Text classification and rationales



An alternative approach:

1. Identify the rationale (the highlighted words)

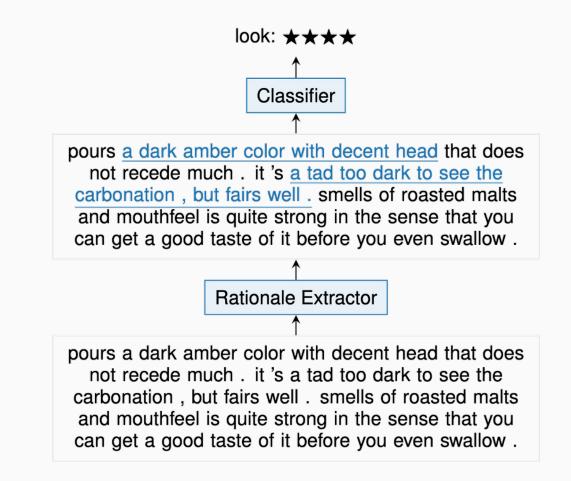
 $Z_i \mid x \sim Bernoulli(g_i(x, \phi))$

For each token, this represents whether the token is relevant or not

```
Each Z_i can be seen as a Boolean proposition
```

Example from Bastings, Jasmijn, Wilker Aziz, and Ivan Titov. "Interpretable Neural Predictions with Differentiable Binary Variables." In *Proceedings of the 57th Annual Meeting of the Association for Computational Linguistics*, pp. 2963-2977. 2019.

Example: Text classification and rationales



An alternative approach:

Identify the rationale (the highlighted words)

 $Z_i \mid x \sim Bernoulli(g_i(x, \phi))$

2. Use only the highlighted words as input to the classifier

 $Y \mid x \sim Categorical(f(x \odot Z, \theta))$

Example from Bastings, Jasmijn, Wilker Aziz, and Ivan Titov. "Interpretable Neural Predictions with Differentiable Binary Variables." In *Proceedings of the 57th Annual Meeting of the Association for Computational Linguistics*, pp. 2963-2977. 2019.

The Gumbel-Softmax trick

A strategy for training with discrete variables

Introduced concurrently by two papers in ICLR 2017:

- Jang, Eric, Shixiang Gu, and Ben Poole. "Categorical Reparameterization with Gumbel-Softmax"
- Maddison, Chris J., Andriy Mnih, and Yee Whye Teh. "The Concrete Distribution: A Continuous Relaxation of Discrete Random Variables"

Combines two ideas:

- 1. The reparameterization trick
- 2. The Gumbel distribution

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The reparameterization trick: Example

Suppose we have a sample from a Gaussian with mean μ and standard deviation σ

 $z \sim \text{Normal}(\mu, \sigma)$

And suppose we have some loss L(z) defined over the sample

Can we compute the gradient of *L* with respect to the parameters of the Gaussian?

The reparameterization trick: Example

Suppose we have a sample from a Gaussian with mean μ and standard deviation σ

 $z \sim \text{Normal}(\mu, \sigma)$

And suppose we have some loss L(z) defined over the sample

Can we compute the gradient of *L* with respect to the parameters of the Gaussian?

No. When we sample z, we have broken the dependency between L and μ , σ

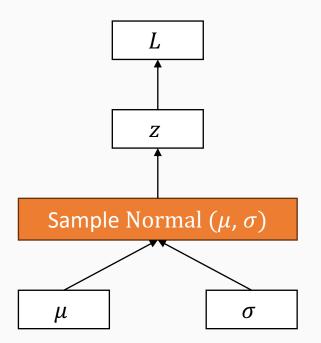
Let's rewrite the Gaussian sample

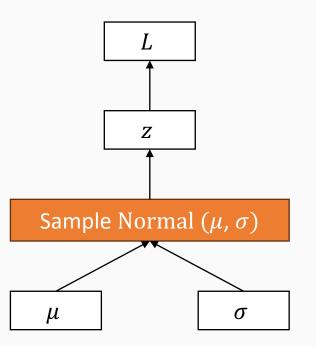
Instead of writing $z \sim \text{Normal}(\mu, \sigma)$, we can write

 $\epsilon \sim \text{Normal}(0, 1)$ $z = \mu + \sigma \epsilon$

Now the desired function L(z) has a direct dependency on μ and σ

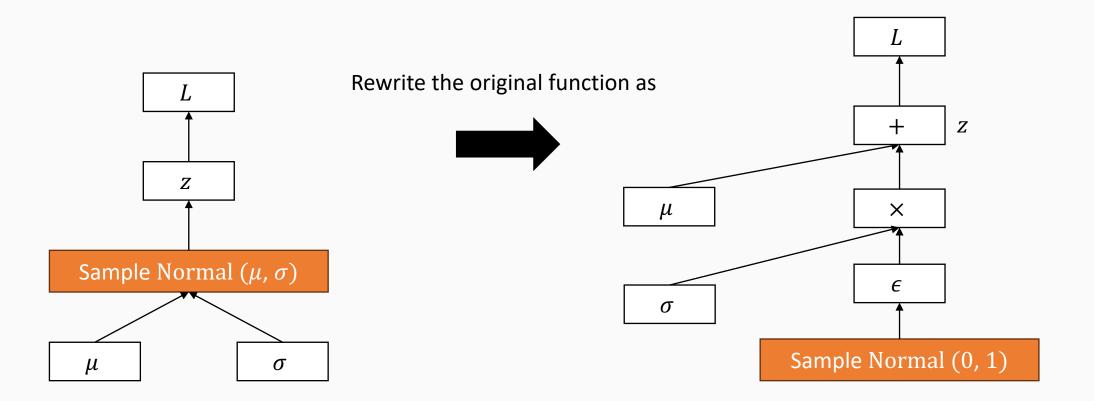
We can take derivatives of L with respect to them





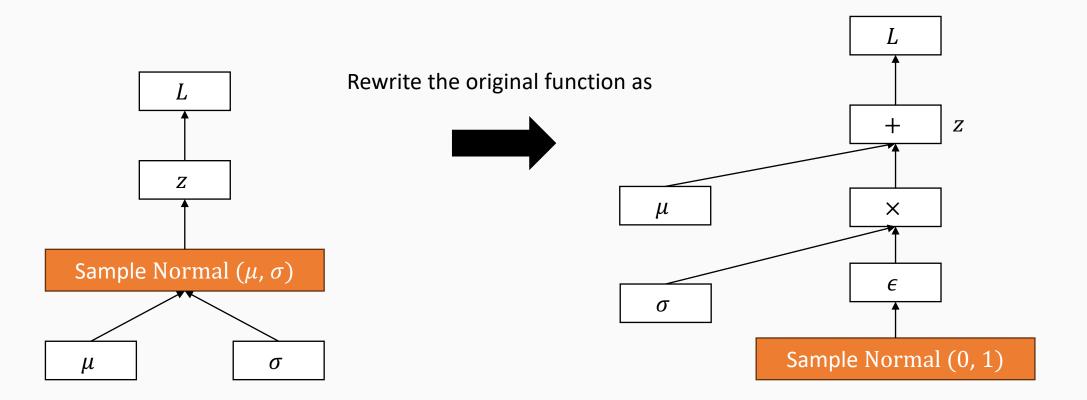
No backward path from the loss to the parameters because of the stochastic node

Cannot compute gradient ⊗



No backward path from the loss to the parameters because of the stochastic node

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No backward path from the loss to the parameters because of the stochastic node

Cannot compute gradient Θ

Stochastic node does not block any gradient computation with respect to μ and σ

Suppose we have $z \sim f(x, \phi)$ and $L(x, \phi, \theta) = g(z, \theta)$

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 $abla_{ heta} L$ is easy, so let us focus on $abla_{oldsymbol{\phi}} L$

Suppose we have $z \sim f(x, \phi)$ and $L(x, \phi, \theta) = g(z, \theta)$

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L is now a differentiable function of the parameters

The Gumbel-Softmax trick

A strategy for training with discrete variables

Introduced concurrently by two papers in ICLR 2017:

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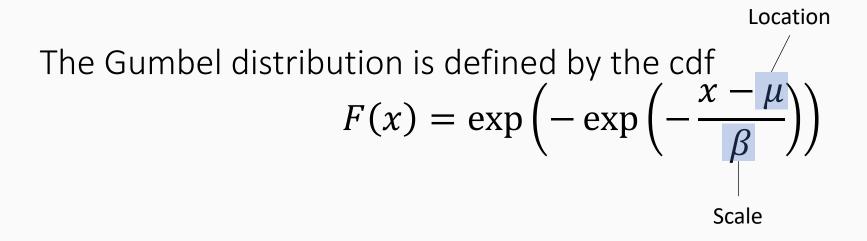
Combines two ideas:

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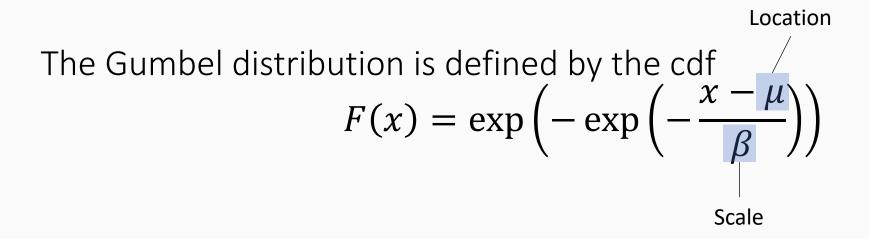
Models the distribution of the max of a set of samples from an exponential distribution

The Gumbel distribution is defined by the cdf $F(x) = \exp\left(-\exp\left(-\frac{x-\mu}{\beta}\right)\right)$

Models the distribution of the max of a set of samples from another distribution



Models the distribution of the max of a set of samples from another distribution



For the "standard" Gumbel distribution, we have $\mu = 0, \sigma = 1$

Models the distribution of the max of a set of samples from another distribution

The Gumbel distribution is defined by the cdf $F(x) = \exp\left(-\exp\left(-\frac{x-\mu}{\beta}\right)\right)$

Sampling from this distribution is easy $g \sim -\log(-\log(\text{Uniform}(0, 1)))$

Models the distribution of the max of a set of samples from another distribution

The Gumbel distribution is defined by the cdf $F(x) = \exp\left(-\exp\left(-\frac{x-\mu}{\beta}\right)\right)$

Sampling from this distribution is easy

 $g \sim$ numpy.random.Generator.gumbel

method

random.Generator.gumbel(loc=0.0, scale=1.0, size=None)

Draw samples from a Gumbel distribution.

Draw samples from a Gumbel distribution with specified location and scale. For more information on the Gumbel distribution, see Notes and References below.

Suppose we have a set of real valued scores x_1, x_2, \dots, x_k assigned to k discrete categories

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The argmax is a sample from the desired distribution!

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Exercise: How would you prove this?

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Reduces the problem of estimating a sample from a distribution to a maximization problem

The argmax is a sample from the desired distribution!

The Gumbel-Softmax trick

A strategy for training with discrete variables

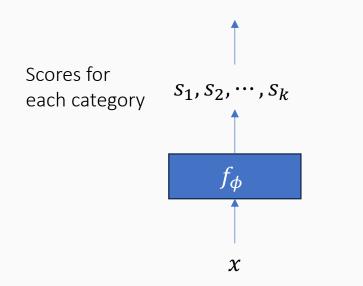
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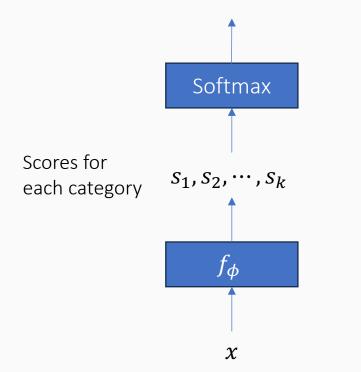
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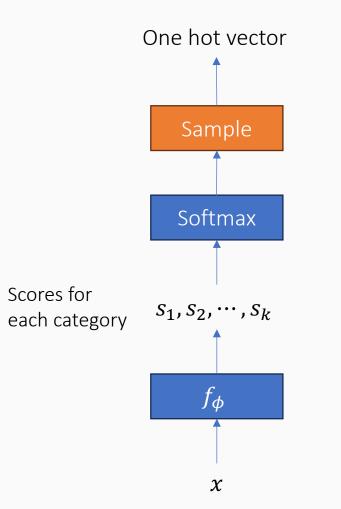
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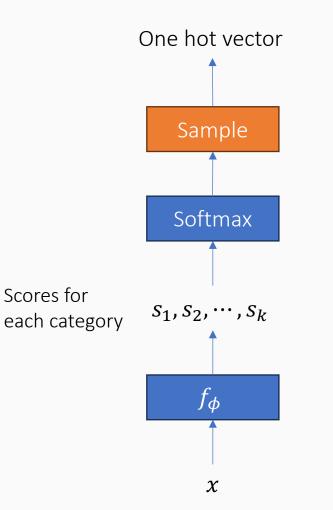
This corresponds to a categorical distribution via softmax



Suppose we have a component of a neural network that produces scores for k categories

This corresponds to a categorical distribution via softmax

And we can sample from the distribution to produce a kdimensional one-hot vector

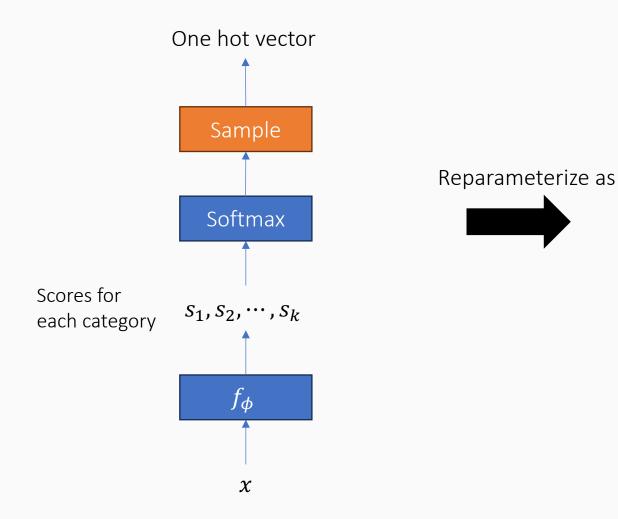


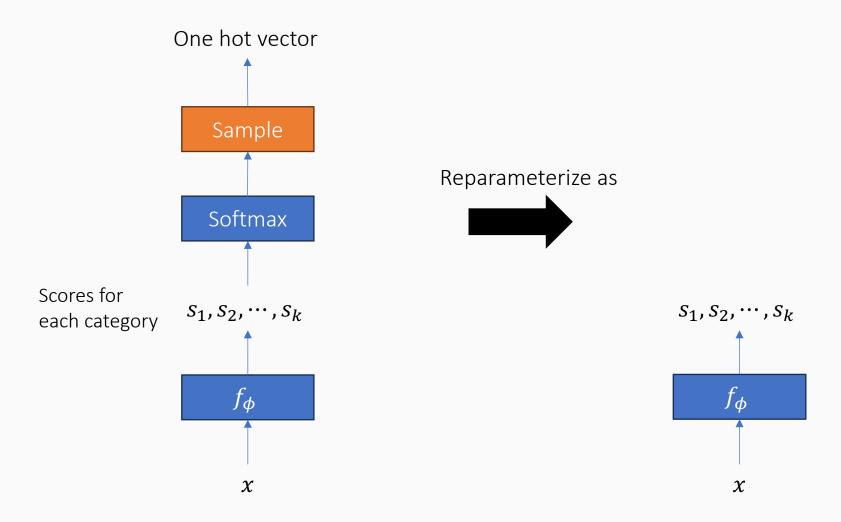
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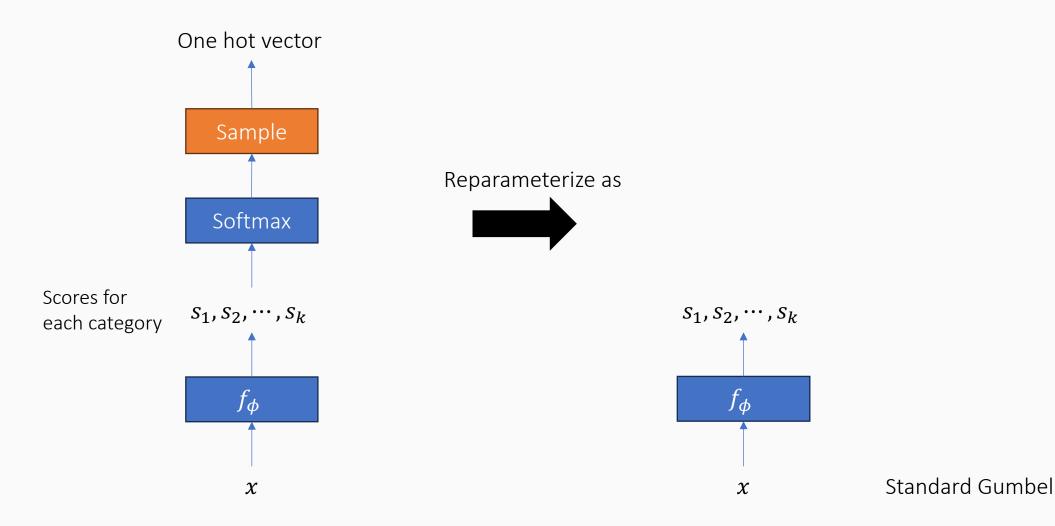
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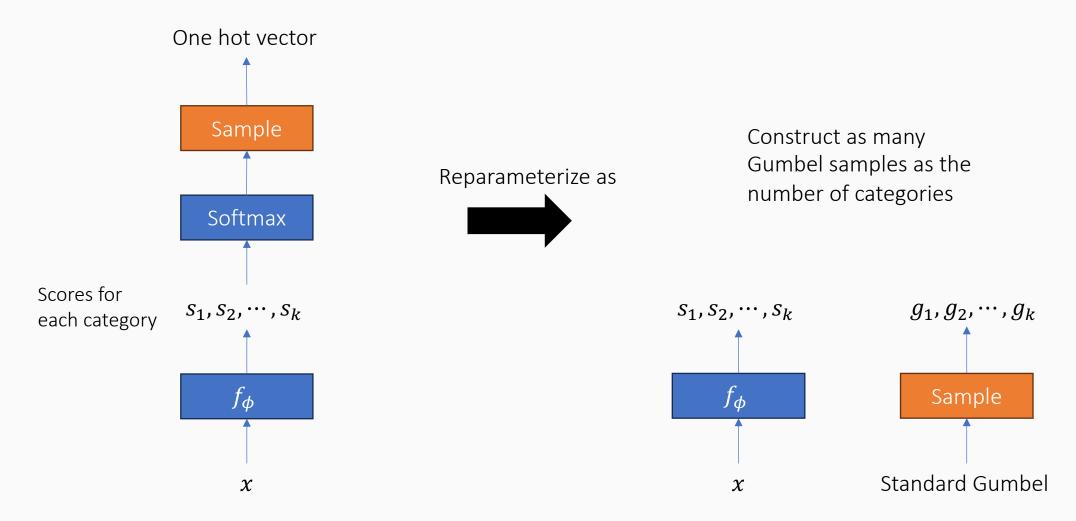
And we can sample from the distribution

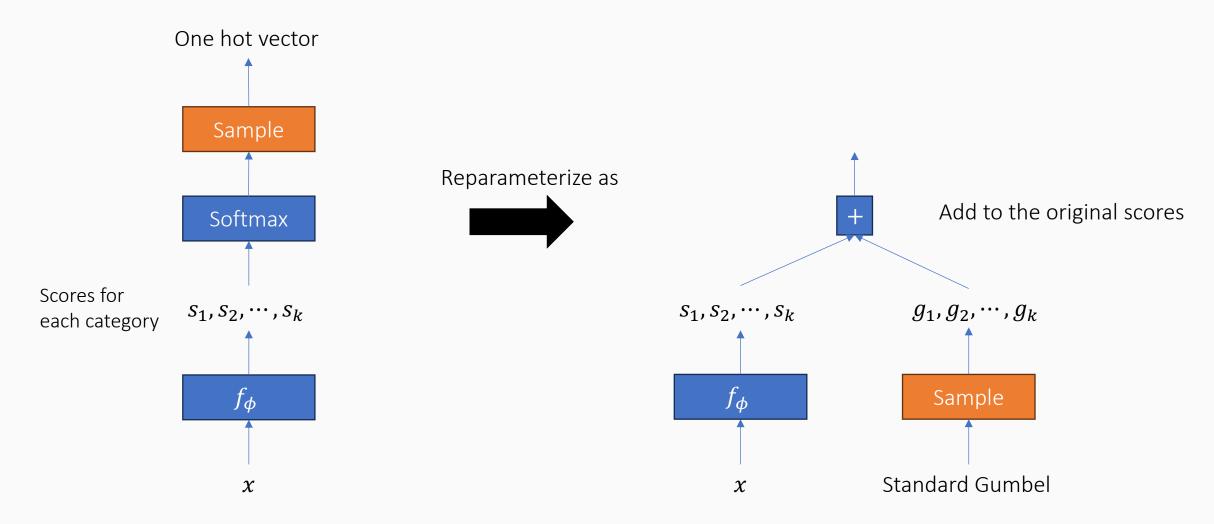
But backprop is no longer viable

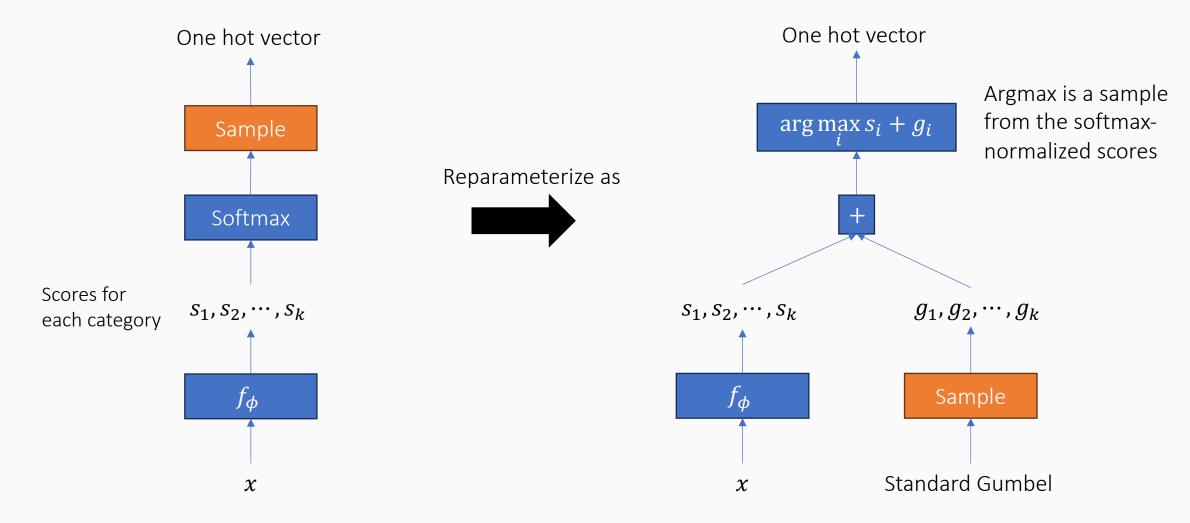


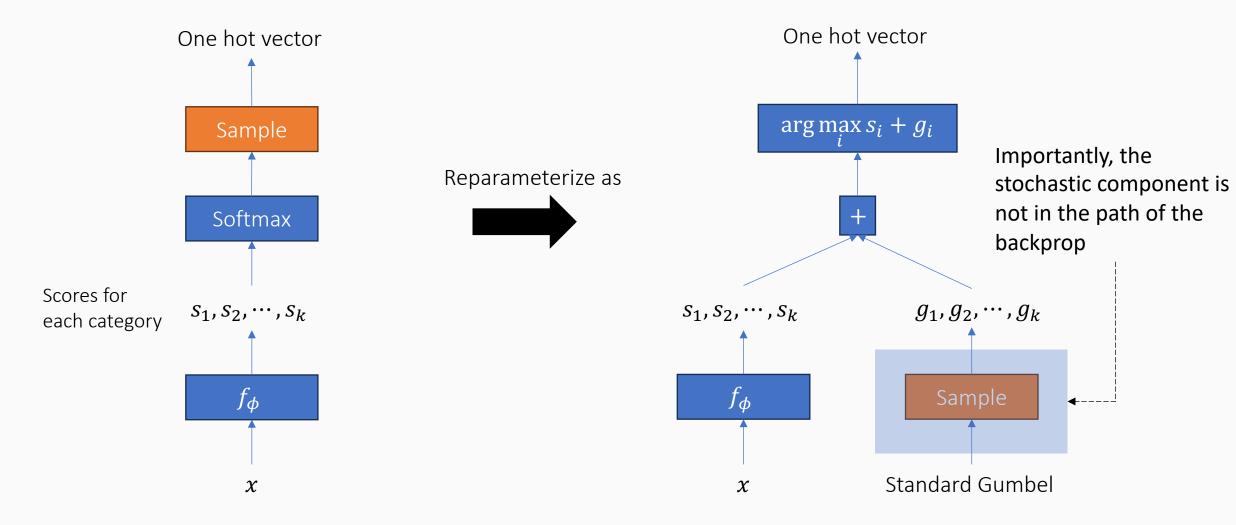


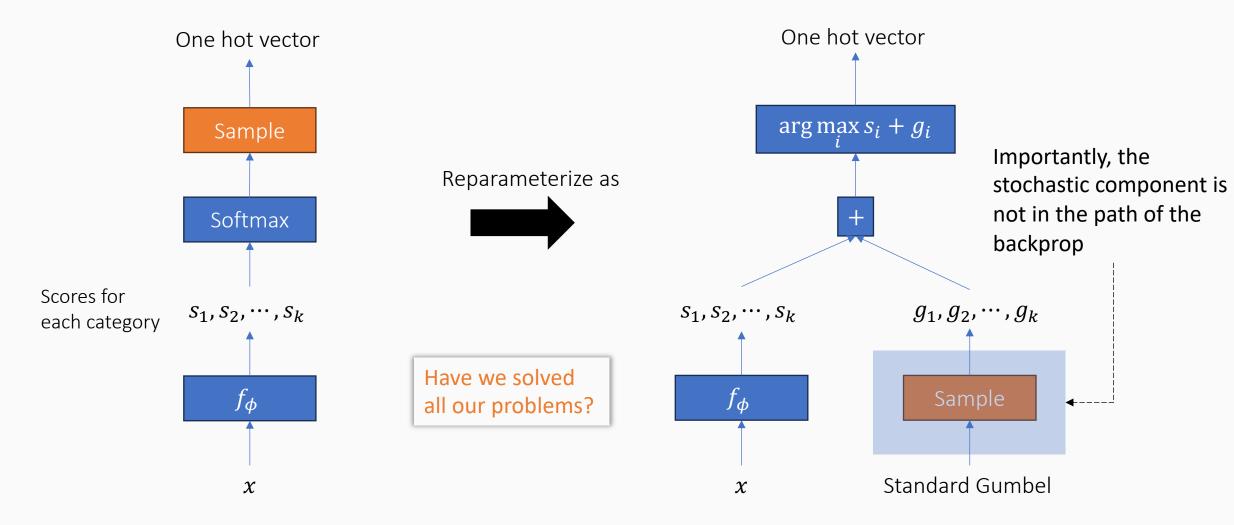


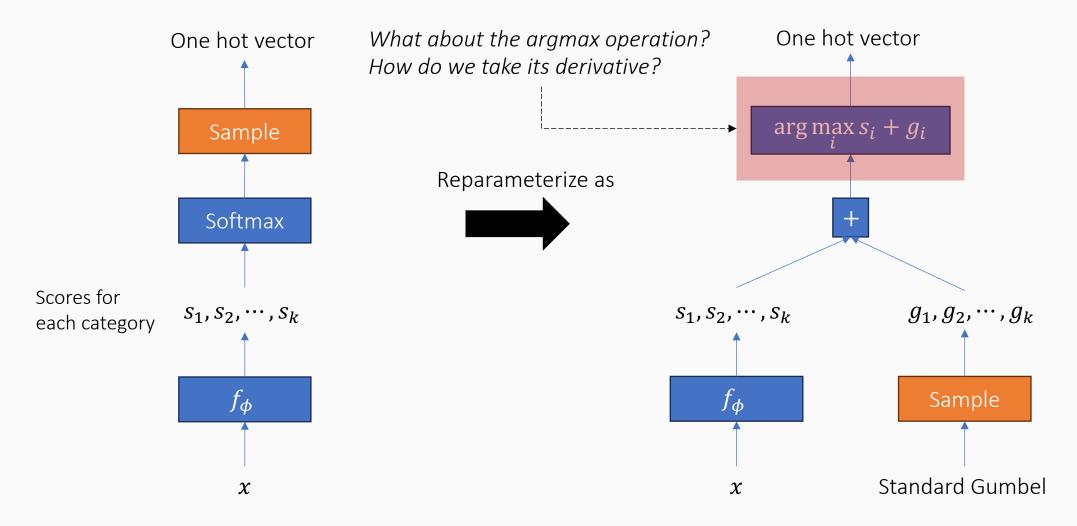




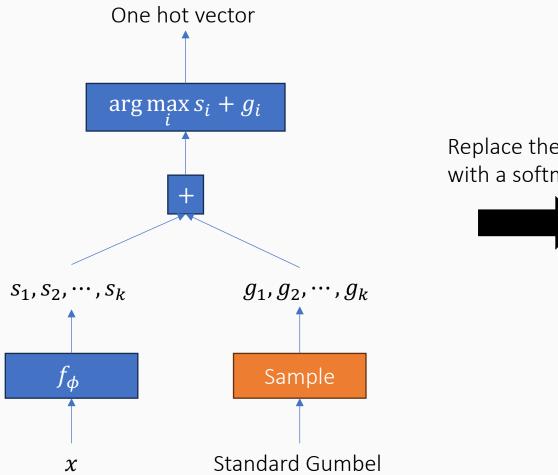








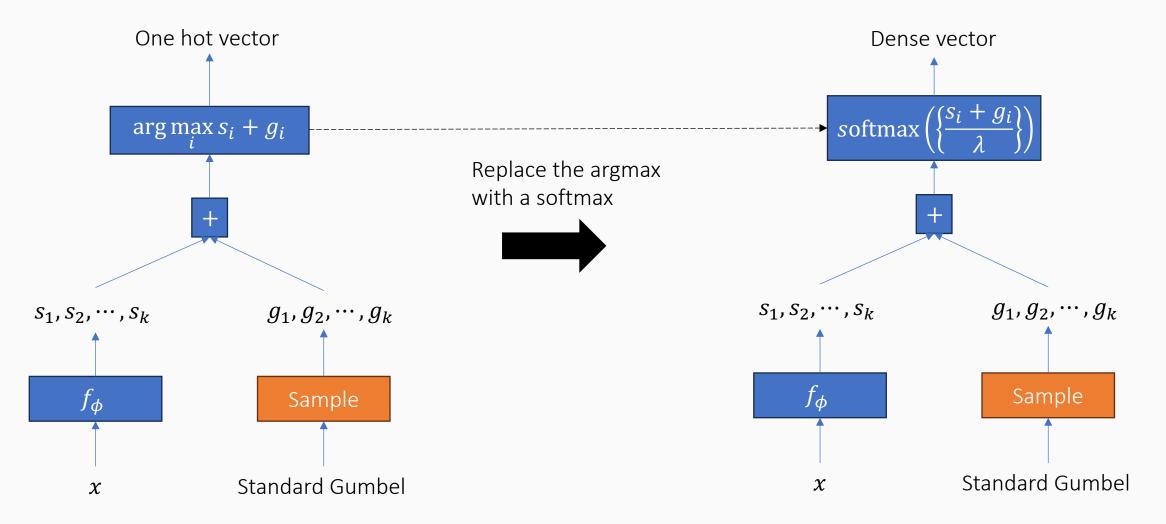
The Gumbel-softmax solution

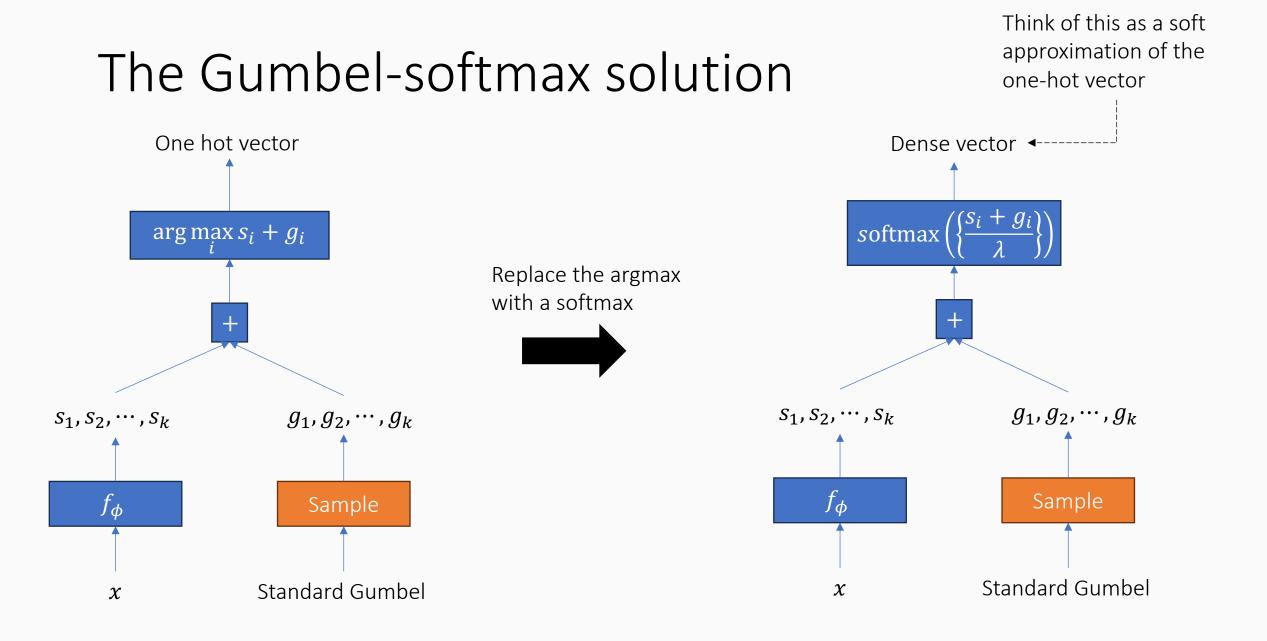


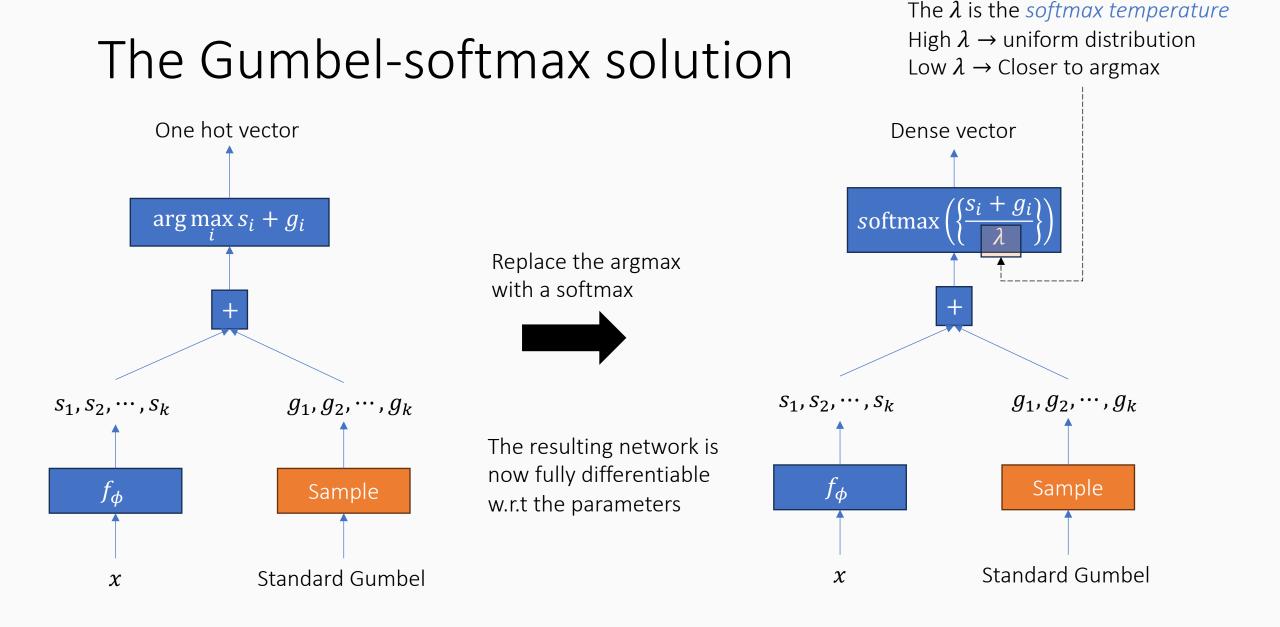
Replace the argmax with a softmax

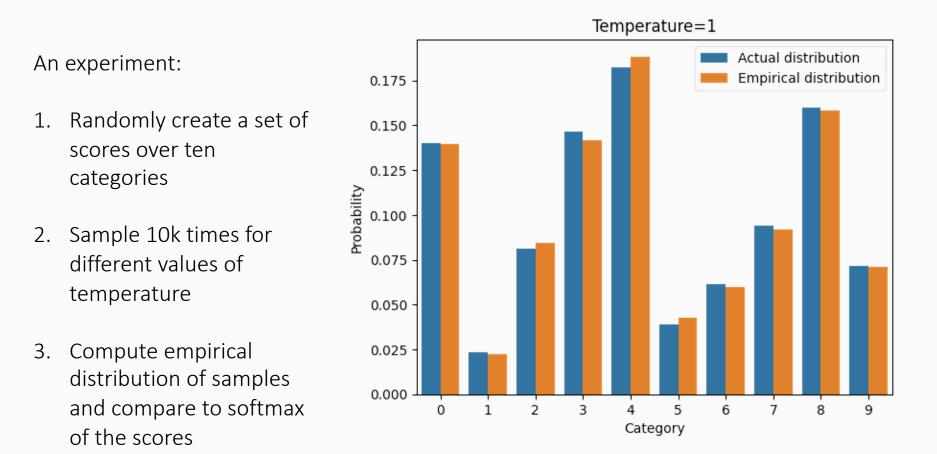


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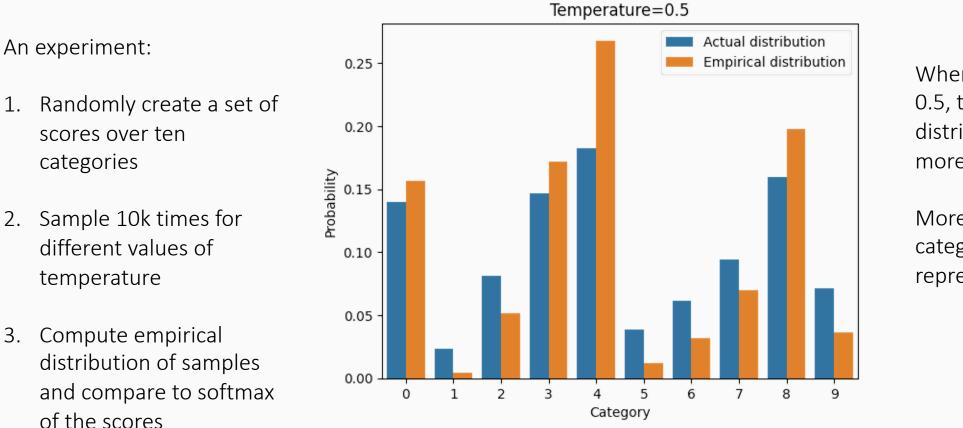






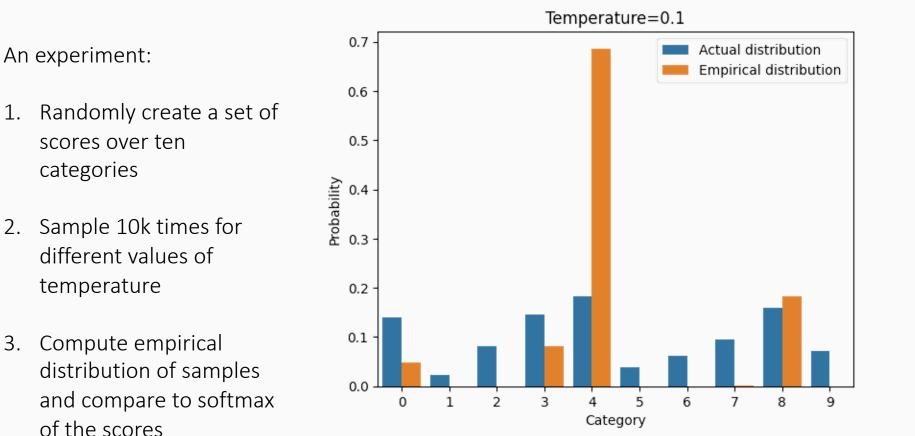


When temperature = 1, the samples represent the true distribution



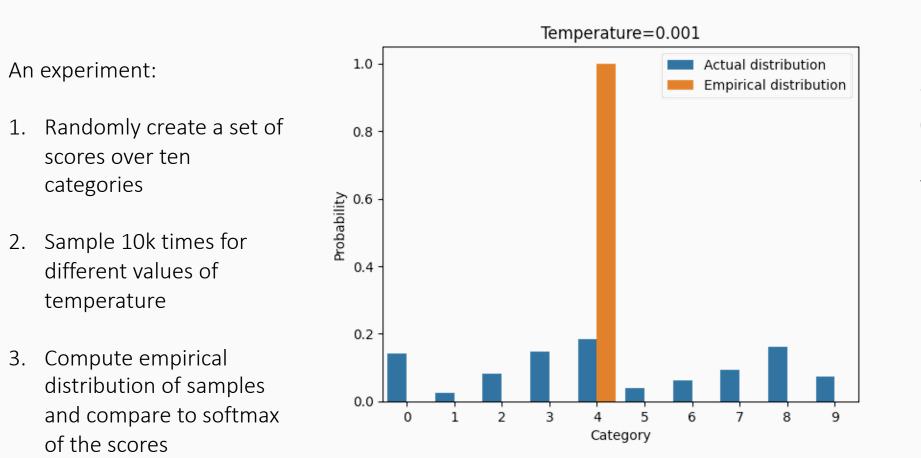
When temperature = 0.5, the empirical distribution becomes more peaky

More probable categories are overrepresented

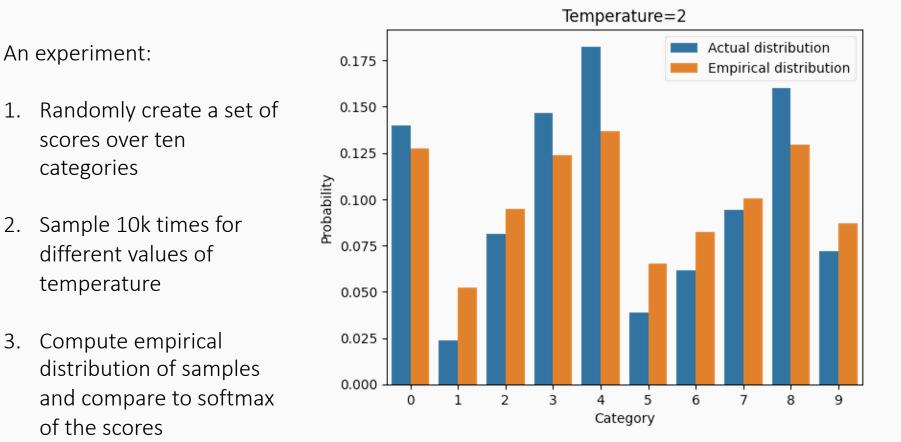


When temperature = 0.1, the peakiness is more visible

Only a few categories show up in the samples



When temperature = 0.001, only the most probable category (i.e. the argmax) is sampled

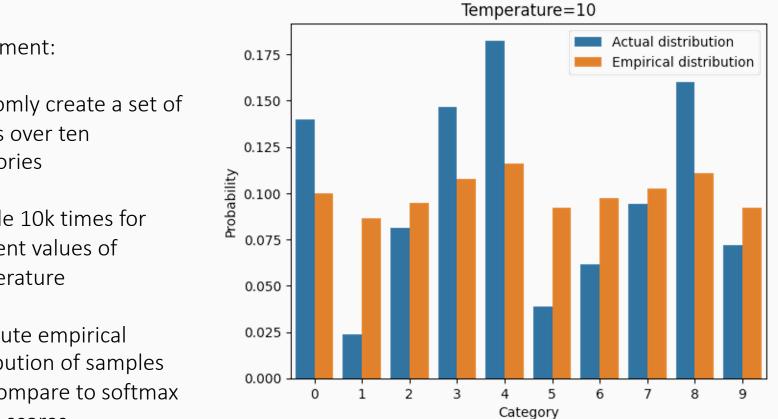


1.

3.

When the temperature is increased to 2, the empirical distribution becomes more "flat" than the actual softmax

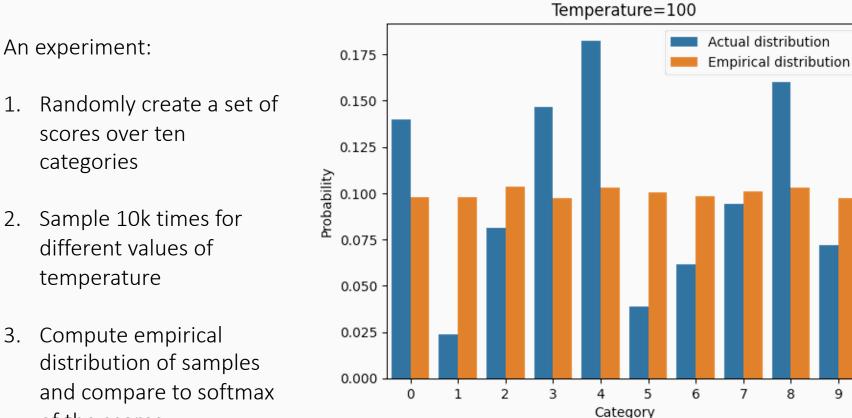
More probable categories are undersampled and less probable ones are oversampled



When the temperature is increased to 10, the "flatness" is more visible

An experiment:

- Randomly create a set of 1. scores over ten categories
- 2. Sample 10k times for different values of temperature
- Compute empirical 3. distribution of samples and compare to softmax of the scores



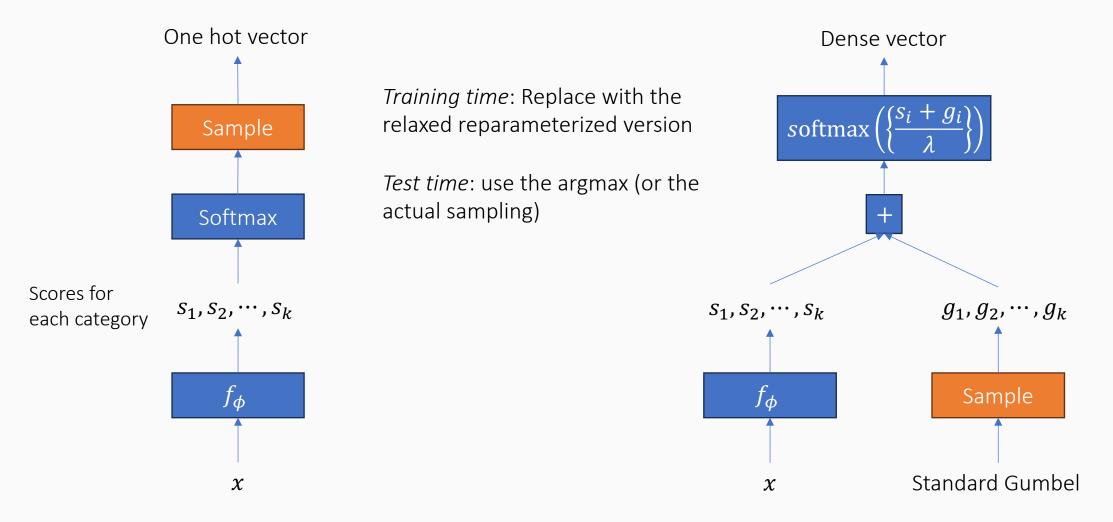
When the temperature is increased to 100, the empirical distribution is nearly uniform

At high temperatures, the underlying scores are ignored

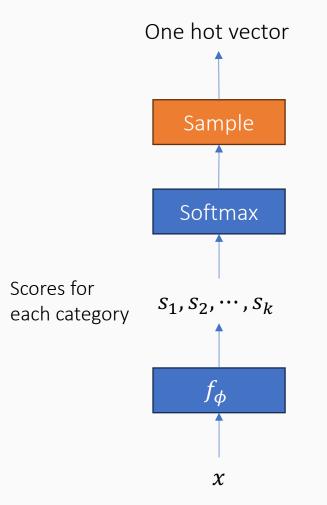
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1.

Using the Gumbel-softmax trick: Approach 1



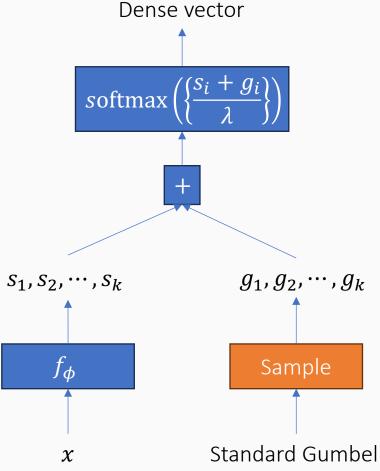
Using the Gumbel-softmax trick: Approach 2



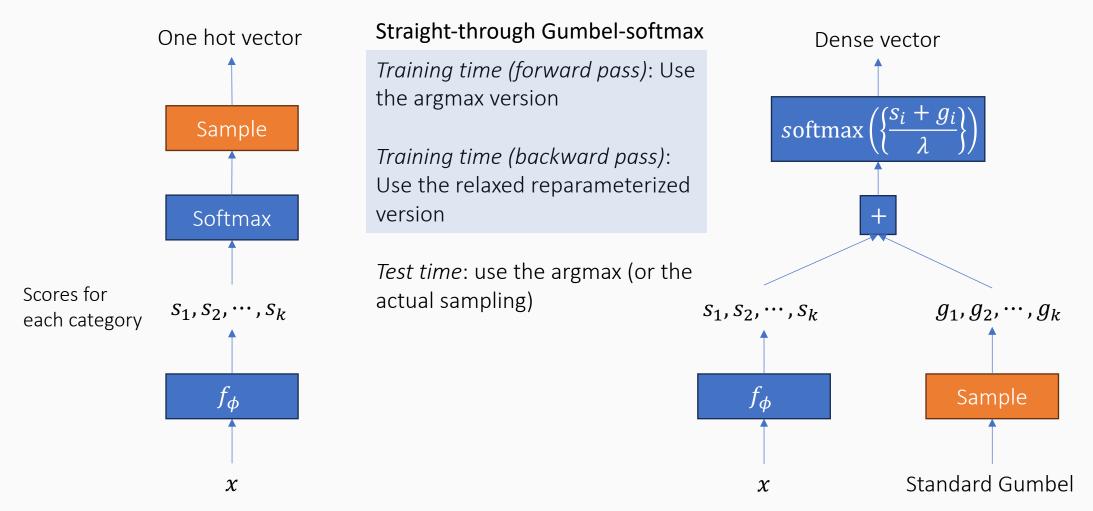
Training time (forward pass): Use the argmax version

Training time (backward pass): Use the relaxed reparameterized version

Test time: use the argmax (or the actual sampling)



Using the Gumbel-softmax trick: Approach 2



Gumbel-softmax: Takeaways

Helps train models that have a categorical sampling node in them

- Important: Does not have to be multiclass sampling, more complicated structures possible as well
- Any discrete distribution can be approximated with the Gumbel-max

An easy idea to incorporate in your code

• Can combine with the straight through estimator

The approach is sensitive to the choice of the softmax temperature

- The Concrete paper uses $\lambda = \frac{2}{3}$
- Another approach: Anneal the temperature from a high temperature to a low one while training proceeds